

G2M Research Multi-Vendor Webinar: AI, Self-Driving Cars, and Advanced Storage

Tuesday July 21, 2020 (v2.0)



WEKA



nVIDIA[®]

▶ Webinar Agenda

- 9:00-9:05** Ground Rules and Webinar Topic Introduction (G2M Research)
- 9:06-9:35** Sponsoring Vendor presentations on topic (10 minute each)
- 9:36-9:46** Key Question 1 (2-minute question; 3 minutes response per vendor)
- 9:47-9:49** Audience Survey 1 (1 minutes)
- 9:49-9:59** Key Question 2 (2-minute question; 3 minutes response per vendor)
- 10:00-10:01** Audience Survey 2 (2 minutes)
- 10:02-10:12** Key Question 3 (2-minute question; 3 minutes response per vendor)
- 10:13-10:23** Audience Q&A (11 minutes)
- 10:24-10:25** Wrap-Up

G2M Research Introduction and Ground Rules

- ▶ Mike Heumann
Managing Partner, G2M Research

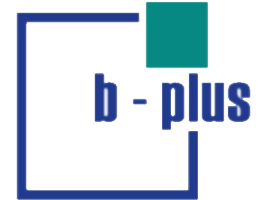
Panelists



Rob Davis
VP, Storage Technology
www.nvidia.com



Alexander Noack
Head of Automotive Electronics
www.b-plus.com



Shailesh Manjrekar
Head of AI, Strategic Alliances
www.weka.io



Mike Heumann
Managing Partner
www.g2minc.com



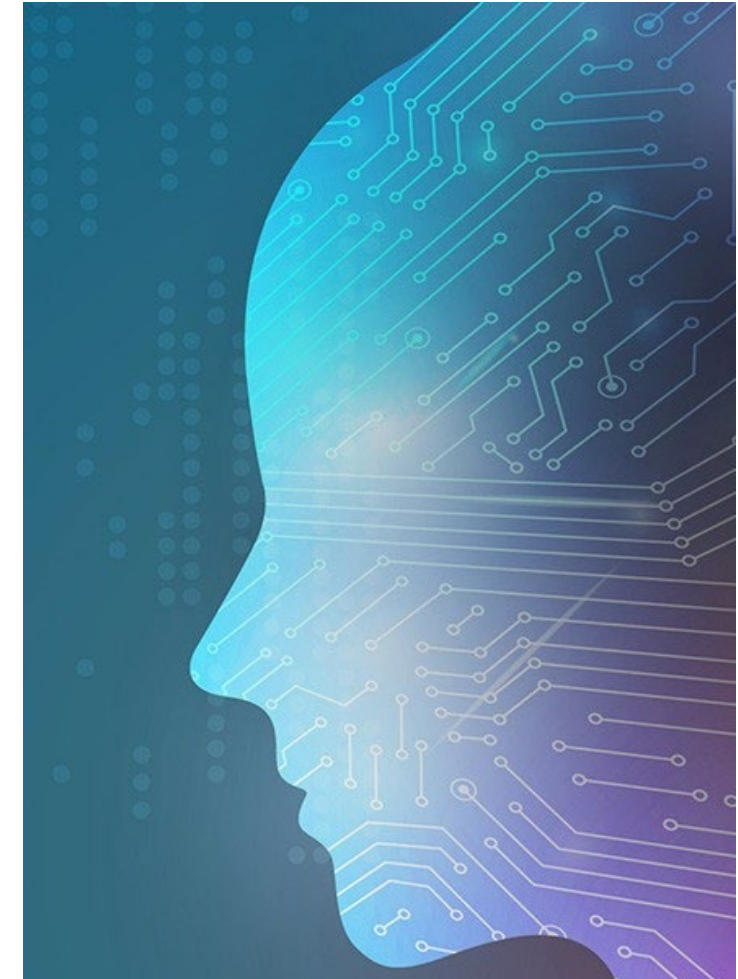
Autonomous Vehicles Success Based on AI/ML

- **Safety is Critical for Self-Driving Cars and Autonomous Vehicles**
 - Tracking objects, pedestrians, and other vehicles is job 1 for self-driving cars
 - Methods such as high-definition maps, path planning, and SLAM drive these capabilities
 - Computer vision, RADAR/LIDAR, and similar technologies support these methods
- **Artificial Intelligence (AI) and Machine Learning (ML) turn this data into vehicle commands**
 - Huge amounts of data is required for both training and vehicle operation



How Much Data Do Self-Driving Cars Need?

- **Training Demands the Most Data**
 - One instrumented car can over 30TB of data per day
 - A fleet of 100 vehicles could generate 780PB of raw data
 - Even with extensive sampling and pre-processing, the data volume will be 100TB-1PB, which would be spread across hundreds of compute nodes during training
- **During driving, storage is used for both operation and for data collection**
 - Data collection likely continues during driving, but it would have to be highly selective (30TB/day is a LOT)
 - Running out of storage has been an issue for Tesla because of this specific issue



NVIDIA

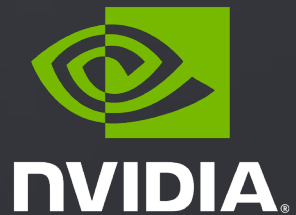


Rob Davis

Vice President Storage Technology, Nvidia Worldwide
Networking Business Unit

www.nvidia.com





AI, SELF-DRIVING CARS, AND ADVANCED STORAGE

Rob Davis, July 2020



NVIDIA AND SELF-DRIVING CARS



NVIDIA DRIVE INFRASTRUCTURE

End-to-End Solutions for Training, Development, and Validation of Autonomous Vehicles.

<https://www.nvidia.com/en-gb/self-driving-cars/infrastructure/>



<https://www.nvidia.com/en-us/self-driving-cars/partners/>

NVIDIA DRIVE SOFTWARE

DRIVE OS

The foundation of the DRIVE Software stack, DRIVE OS is the first safe operating system for accelerated computing. It includes **NvMedia** for sensor input processing, **NVIDIA CUDA** libraries for efficient parallel computing implementations, **NVIDIA TensorRT** for real-time AI inference, and other developer tools and modules to access hardware engines.

DRIVE AV

The DRIVE AV software stack contains the perception, mapping, and planning layers, as well as diverse DNNs trained on high-quality real-world driving data. These rich perception outputs can be used for both autonomous driving and mapping. In the planning and control layer, the **NVIDIA Safety Force Field** computational module checks the actions of the primary planning system to shield the vehicle from collisions.

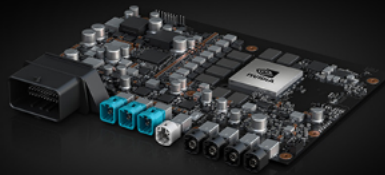
DriveWorks

The **NVIDIA DriveWorks** SDK provides middleware functions on top of DRIVE OS that are fundamental to autonomous vehicle development. These consist of the sensor abstraction layer (SAL) and sensor plugins, data recorder, vehicle I/O support, and a deep neural network (DNN) framework. It's modular, open, and designed to be compliant with automotive industry software standards.

DRIVE IX

DRIVE IX is an open software platform that delivers interior sensing for innovative AI cockpit solutions. It provides perception applications to access features and DNNs for advanced driver and occupant monitoring, AR/VR visualization, and natural language interactions between the vehicle and passengers. DRIVE IX also enables fleet monitoring, event-based in-cabin recording, and remote operation capabilities in trucks.

NVIDIA DRIVE HARDWARE - AGX



NVIDIA DRIVE AGX XAVIER

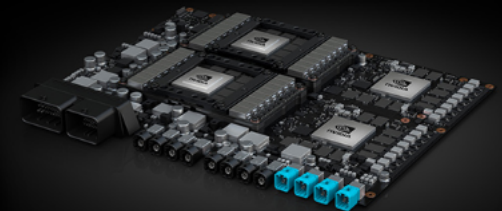
NVIDIA DRIVE AGX Xavier™ delivers 30 trillion operations per second (TOPS) for Level 2+ and Level 3 automated driving. At its core is the first-ever production auto-grade Xavier SoC, which incorporates six different types of processors, including CPU, GPU, Deep Learning Accelerator (DLA), Programmable Vision Accelerator (PVA), Image Signal Processor (ISP), and Stereo/Optical flow accelerator.

[LEARN MORE ABOUT DRIVE AGX XAVIER DEVELOPER KIT >](#)

NVIDIA DRIVE AGX PEGASUS

NVIDIA DRIVE AGX Pegasus™ uses the power of two Xavier SoCs and two NVIDIA Turing™ GPUs to achieve an unprecedented 320 TOPS of supercompute. The platform is designed and built for Level 4 and Level 5 autonomous systems, including robotaxis.

[LEARN MORE ABOUT DRIVE AGX PEGASUS DEVELOPER KIT >](#)



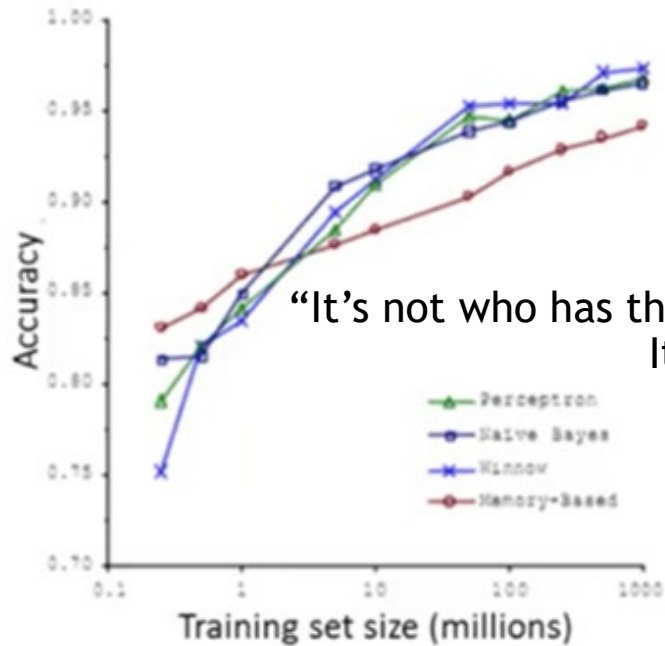
Don't Forget About Storage When Planning For AI And ML



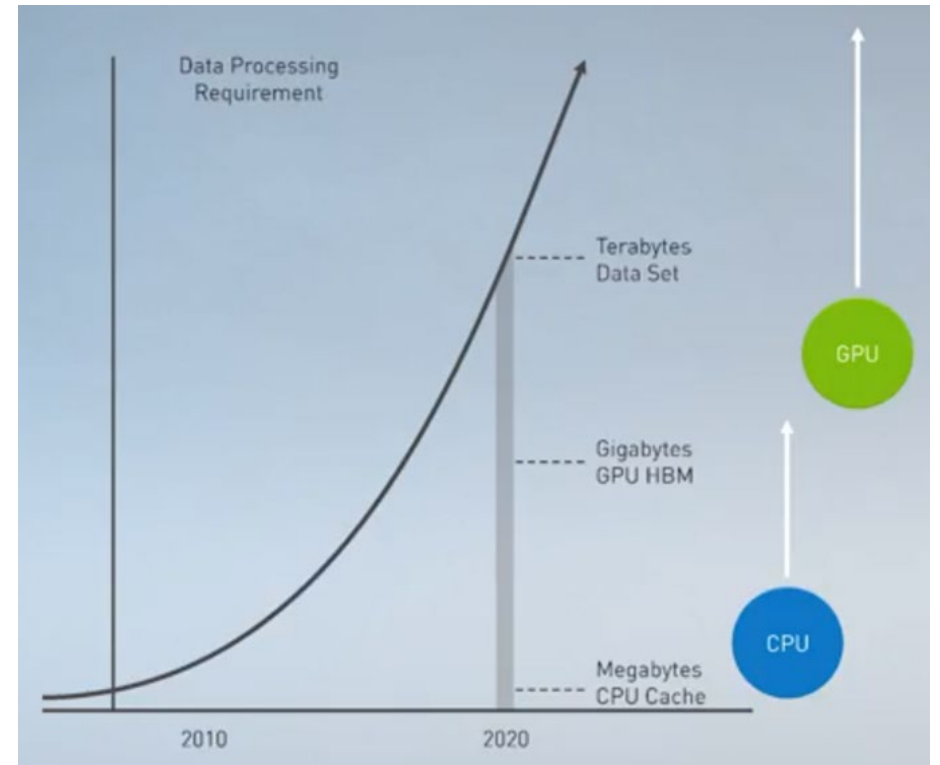
Patrick Moorhead Contributor

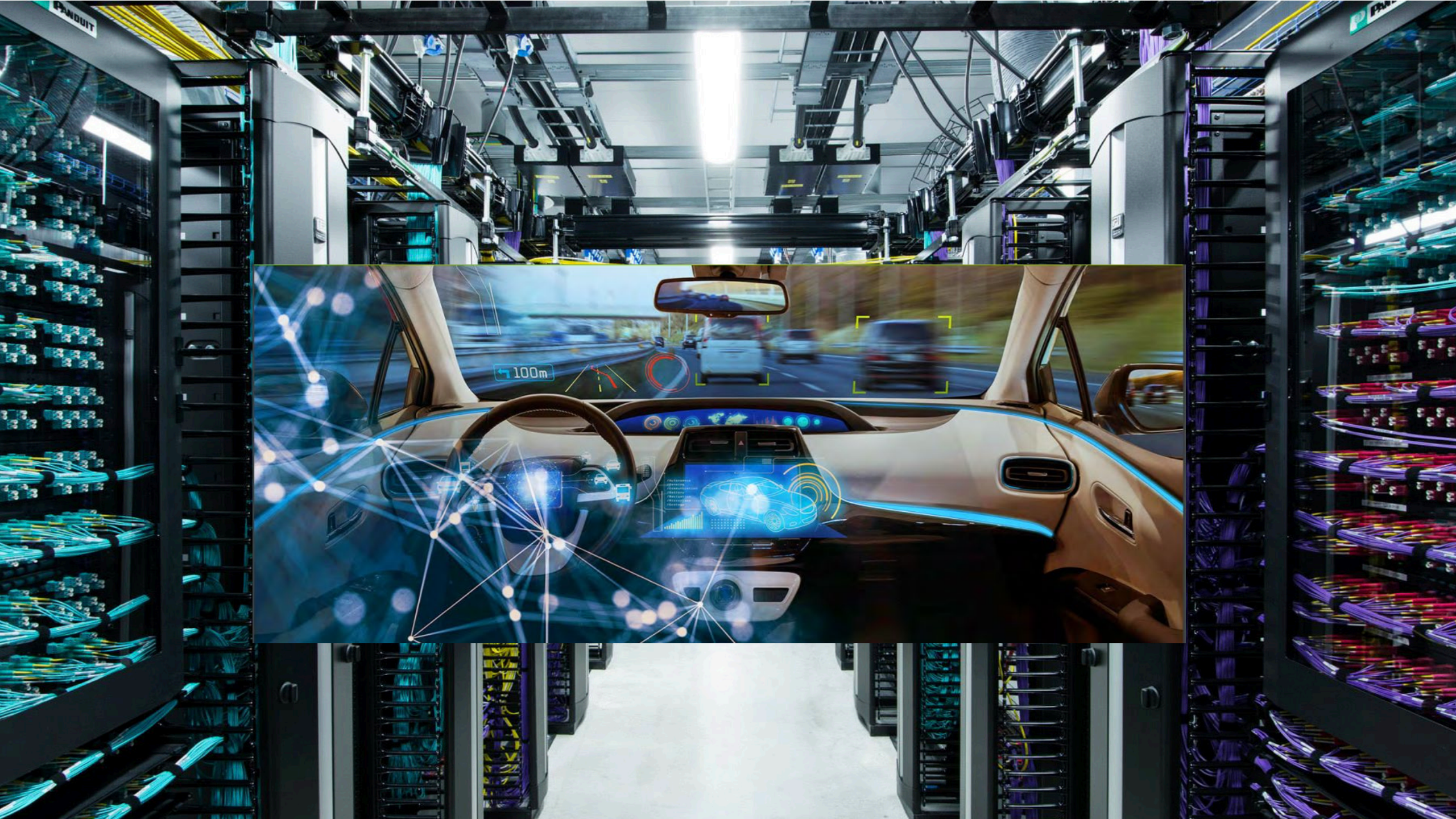
Enterprise & Cloud

I write about disruptive companies, technologies and usage models.

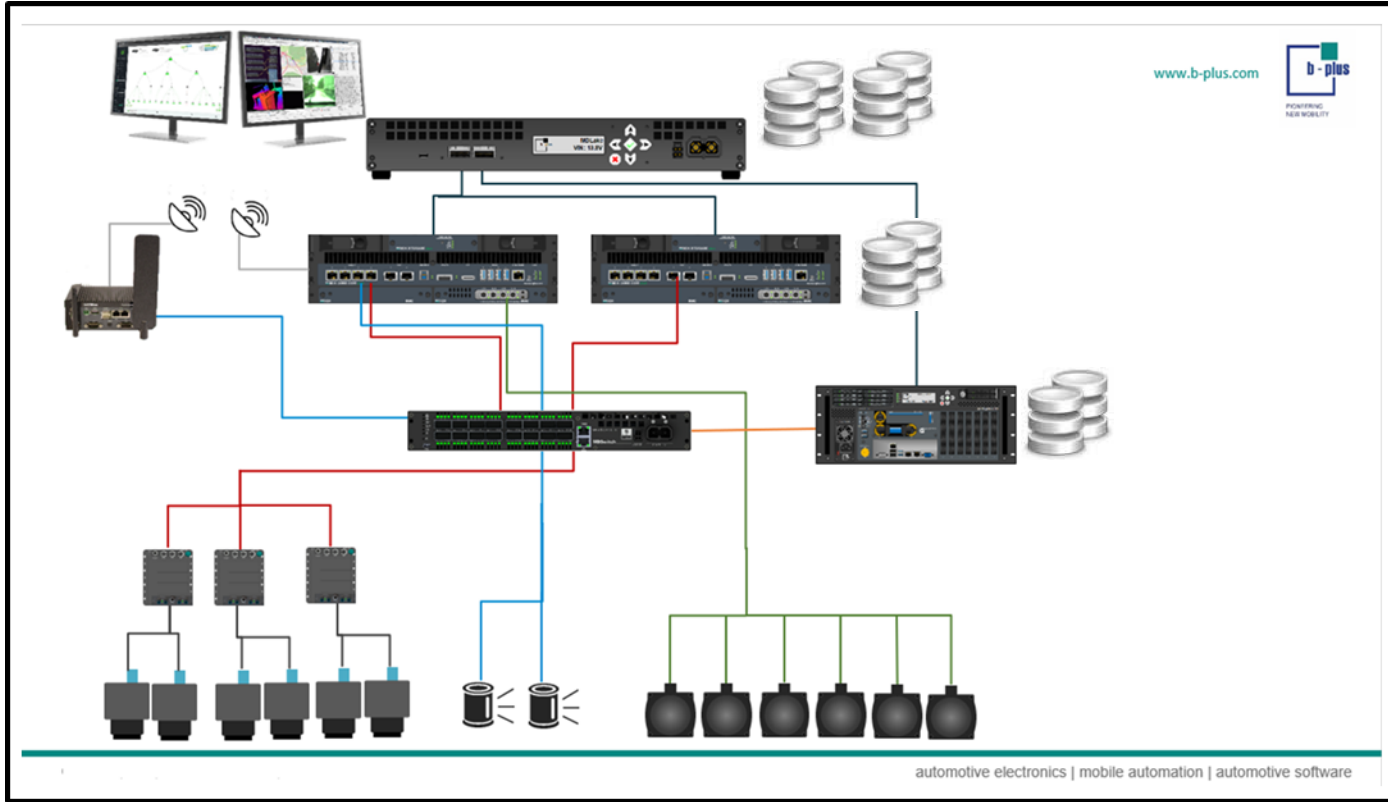


“It’s not who has the best algorithm that wins. It’s who has the most data.”
Andrew Ng

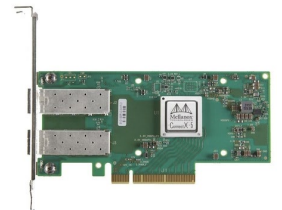
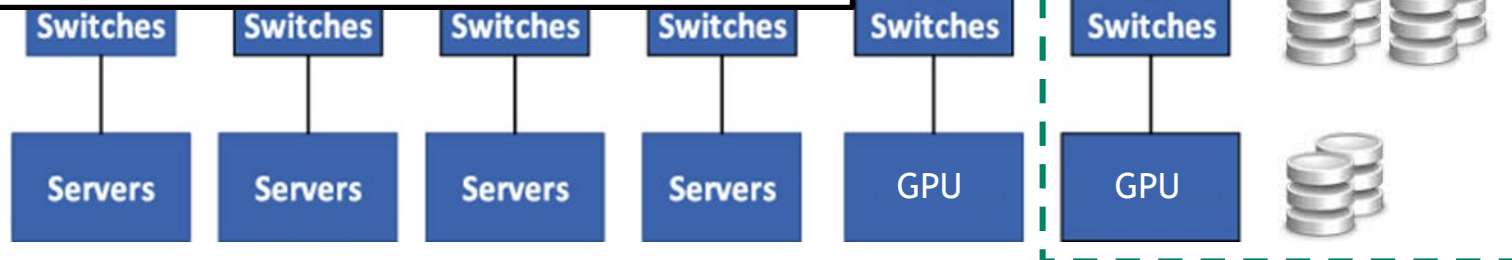




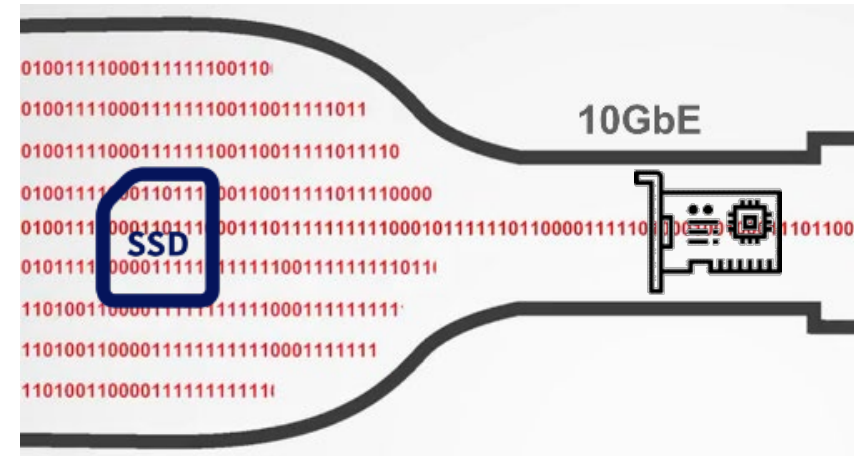
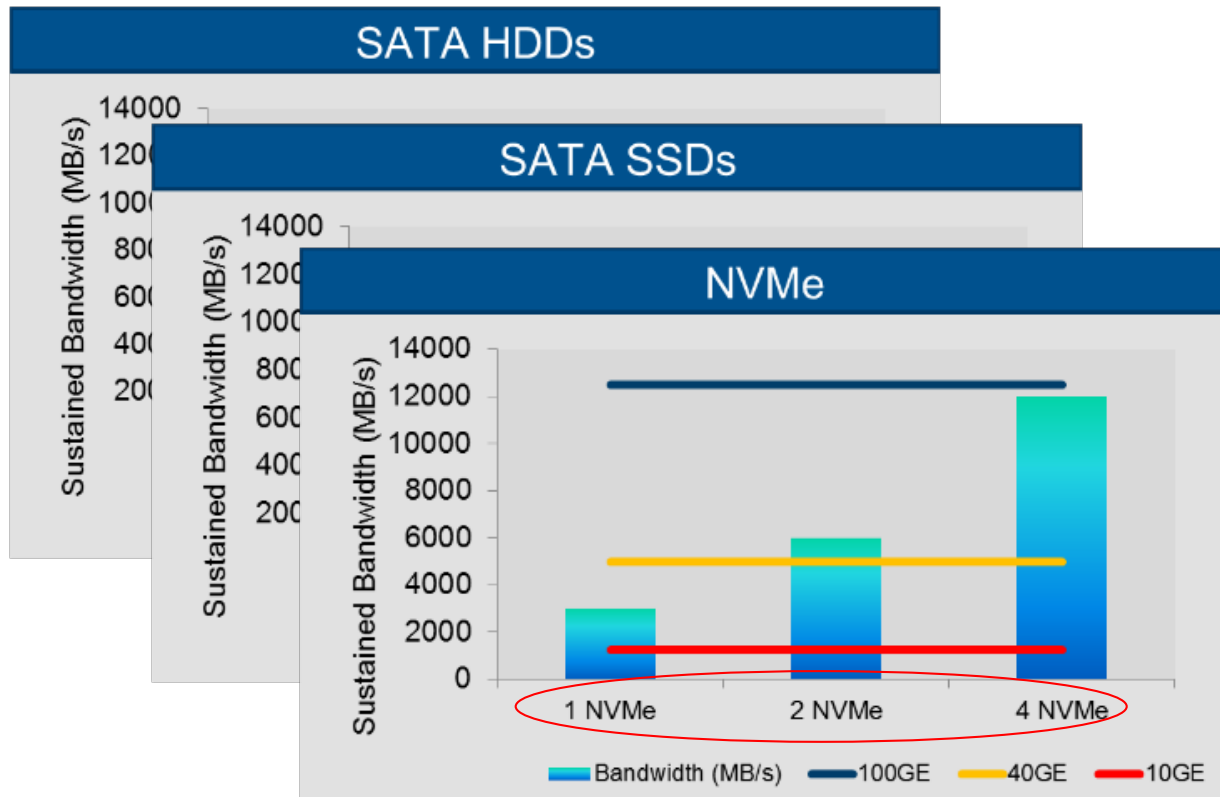
STORAGE NETWORK TOPOLOGY



Key
CR=Core Router
AS=Aggregation Switch
ToR=Top-of-Rack Switch



SSDs Have Changed Networked Storage



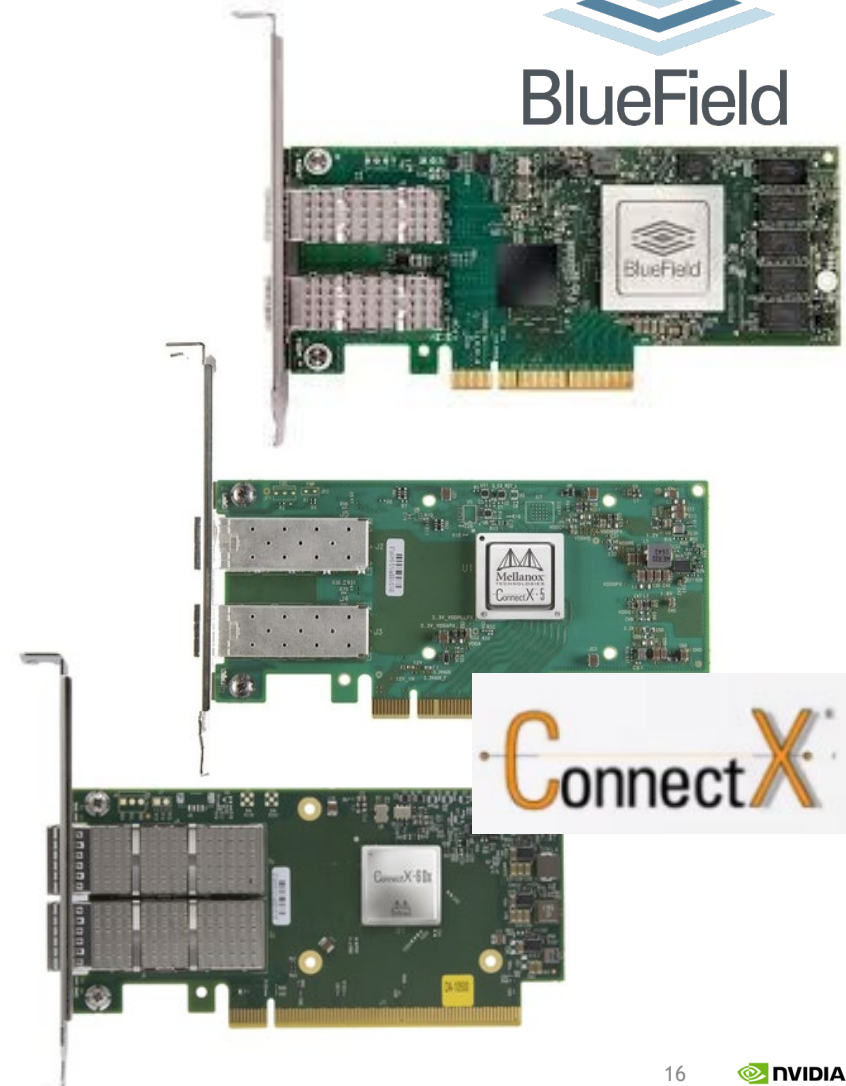
SSDs move the Bottleneck from the Disk to the Network



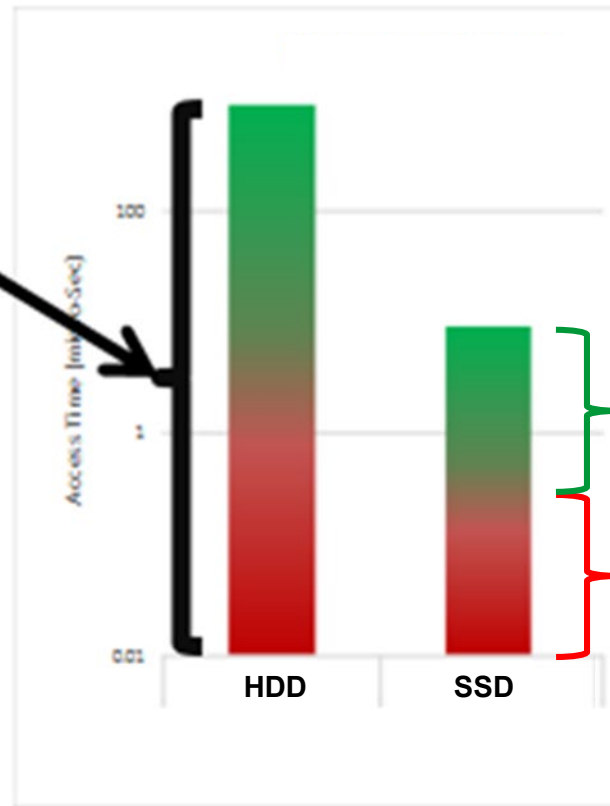
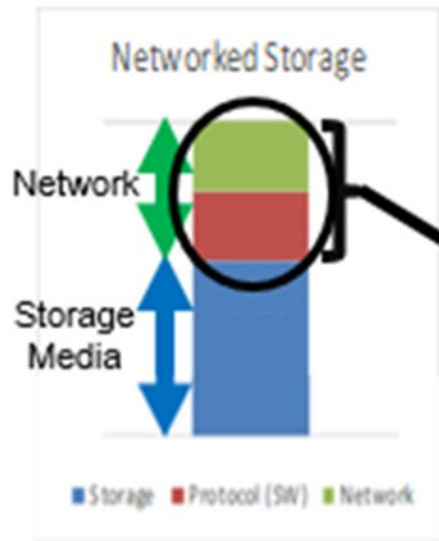
Faster Network Products from Nvidia Solves Half the Network Bottle Neck Problem...



End to End 200Gb/s



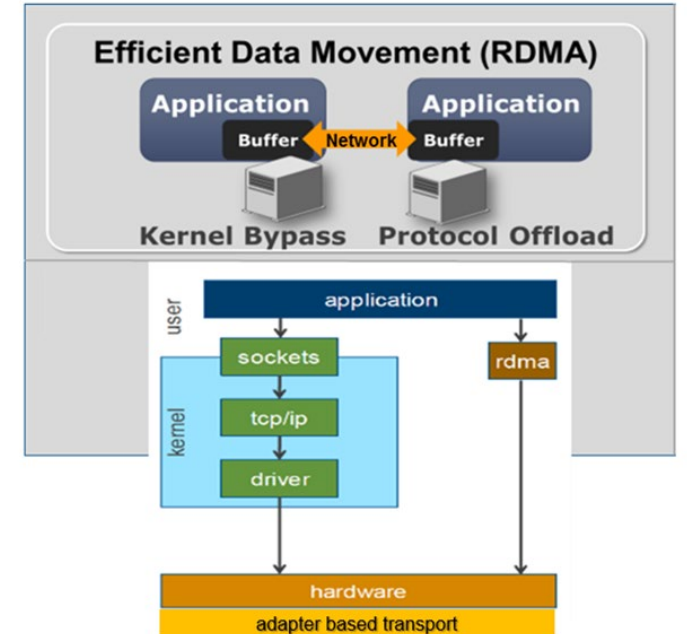
Faster Protocols from Nvidia Solves the Other Half



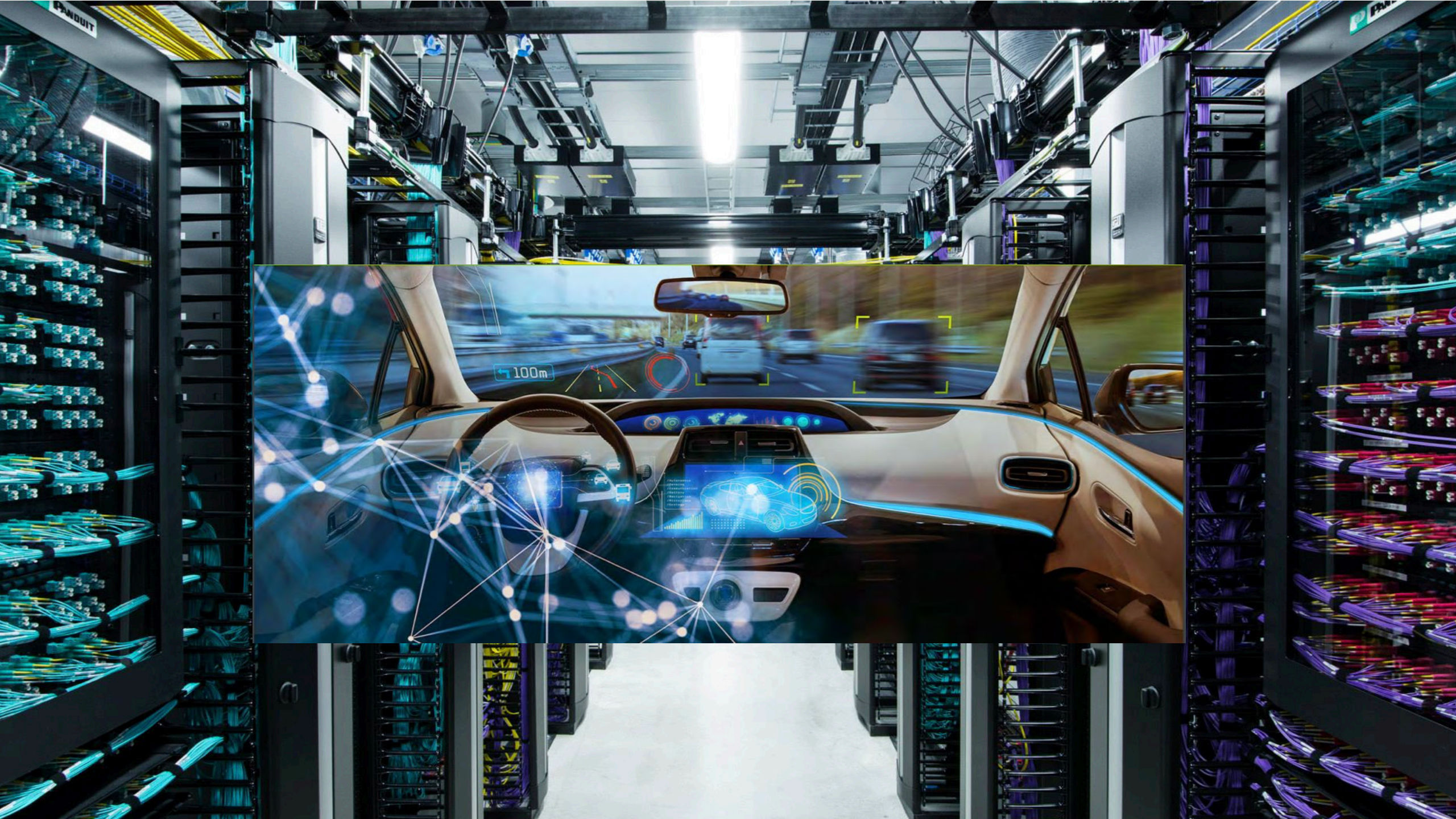
Faster Network

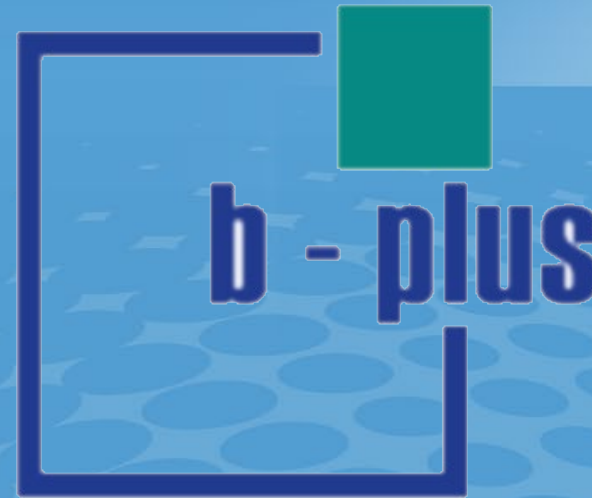
Faster Protocol

NVMe-oF



NVMe OVER FABRICS
POWERED BY RoCE





b-plus

- ▶ Alexander Noack
Head of Automotive Electronics
www.b-plus.com



AI, Self-Driving Cars, and Advanced Storage



PIONEERING NEW MOBILITY.

Who we are

b-plus is partner for the automotive and automation industry.

We develop software and hardware solutions for applications such as driver assistance, autonomous driving, connected car and control of mobile machines.

Tools for autonomous driving

ADAS/AD Multi-Sensor Recording, Visualization and Recording framework, Hardware in the Loop
raw data simulation

b-plus in numbers

Founded: 1996
Employees: 200+

Locations

Deggendorf (Headquarters)
Regensburg
Lindau

AUTONOMOUS CARS



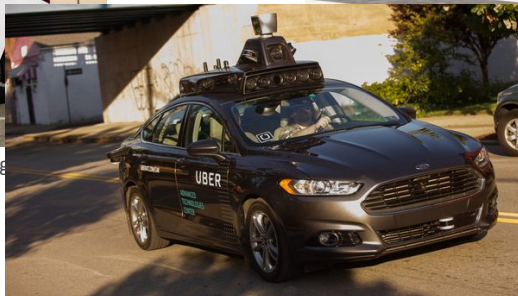
<https://www.wired.com.au/car-news/continental-cool-on-self-driving-cars>



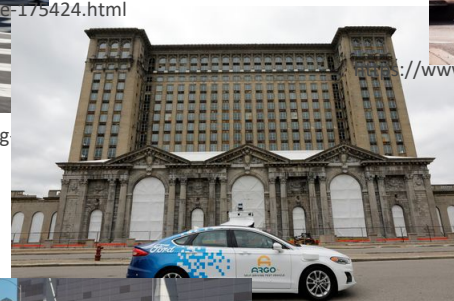
<https://www.south-presse.de/pressportal/de/en/bosch-and-daimler-san-jose-target-to-become-pilot-city-for-an-automated-on-demand-ride-sharing-service-175424.html>



<https://www.bloomberg.com/features/2020-self-driving>



<https://www.bloomberg.com/features/2020-self-driving>



<https://www.bloomberg.com/features/2020-self-driving-car-race/>



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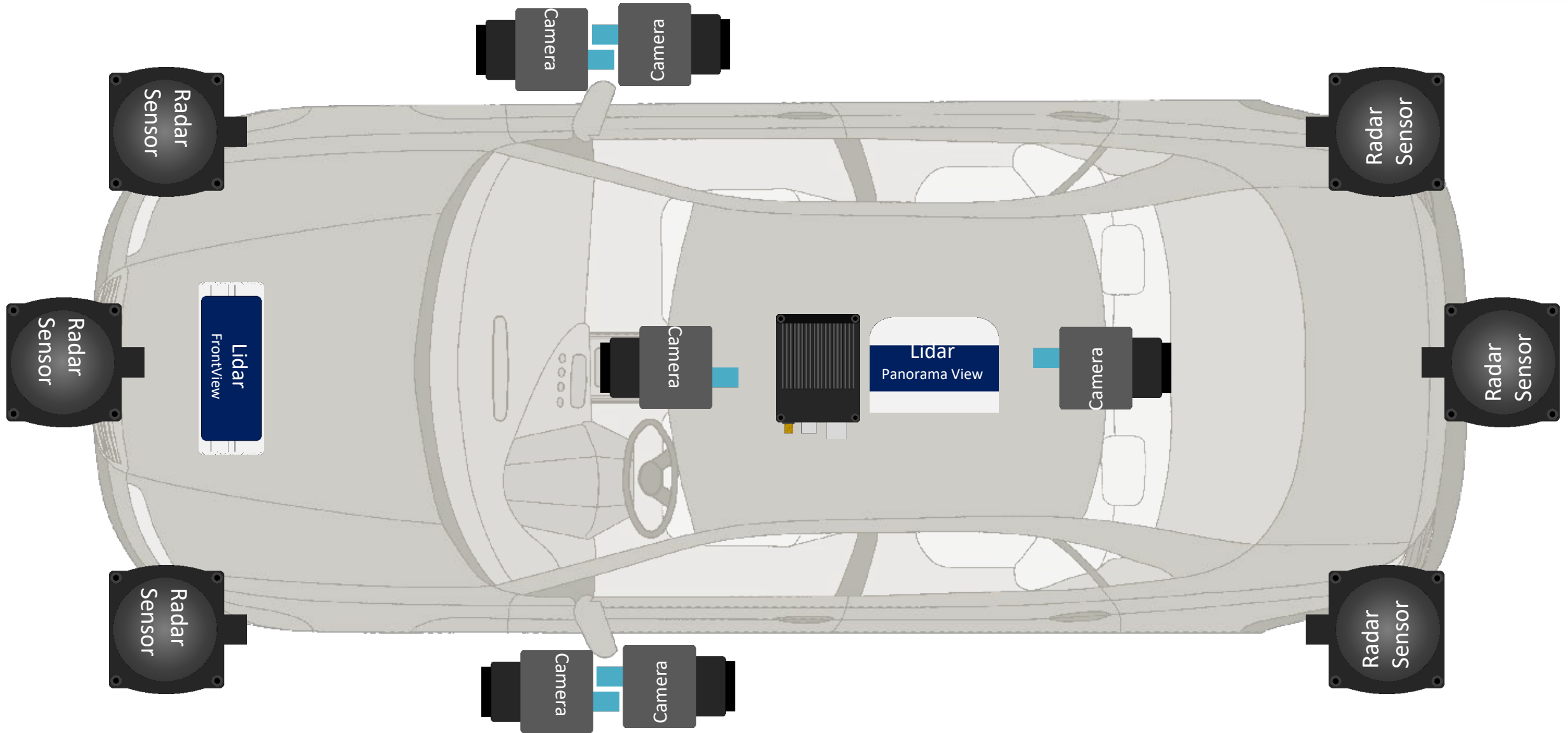


<https://www.bloomberg.com/features/2020-self-driving-car-race/>



https://www.zf.com/site/magazine/en/articles_16141.html

SAMPLE CONFIGURATION



Terabytes generated per vehicle

Data rate examples:

1x Camera (Full HD/RAW12/40fps) \approx 120 MB/s

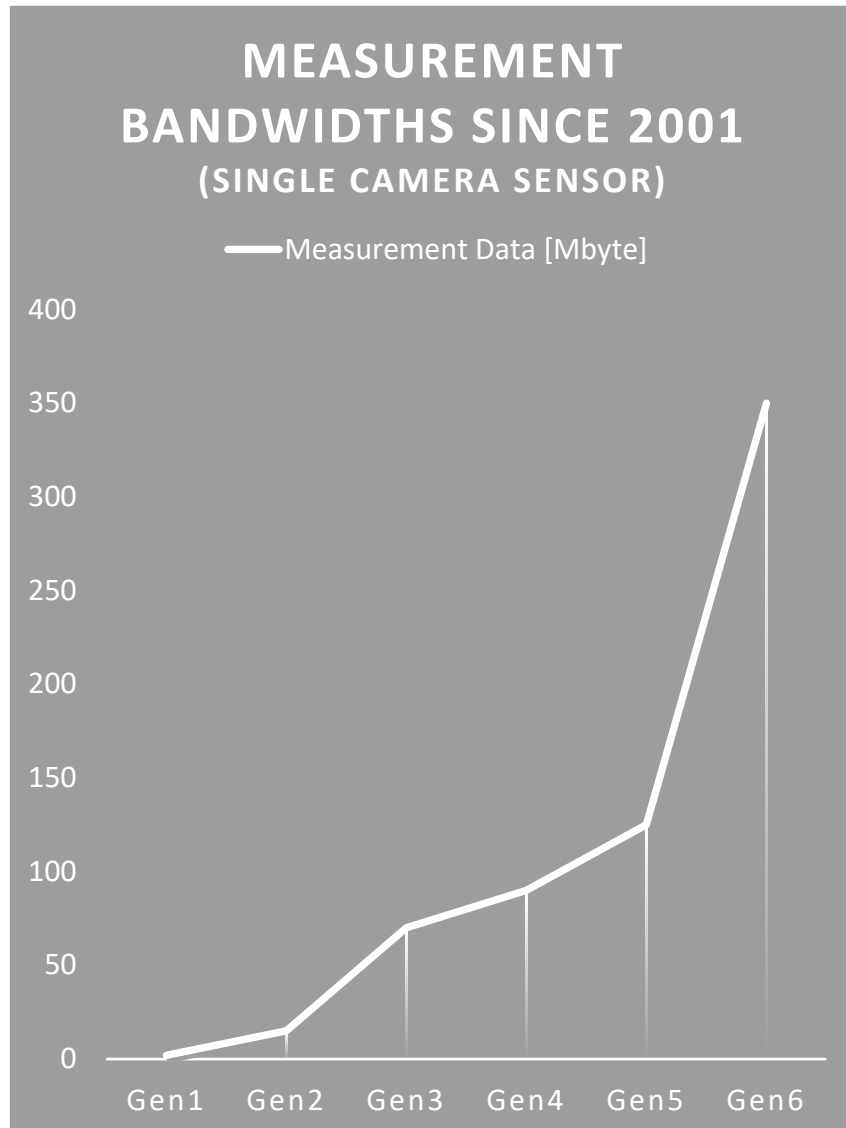
1x Radar \approx 220 MB/s

Example setup:

6 Cameras and 6 Radars

Complete vehicle RAW data \approx 2.040 MB/s

\approx **58 TB** in a 8h test drive shift

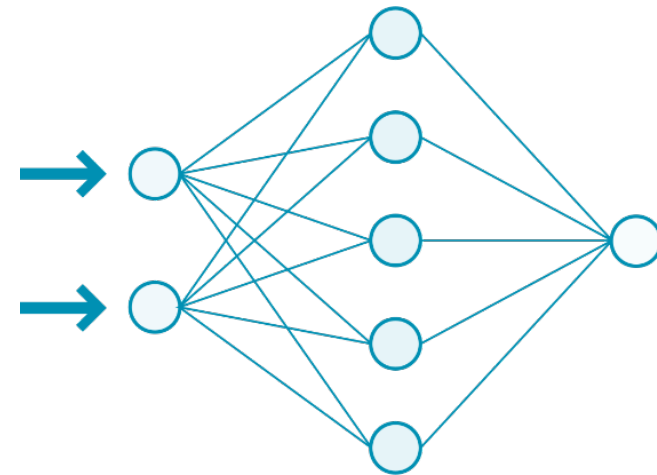


Data driven development (Neural networks) needs accurate data

- Therefore accurate data is the key to a successful function
- How accurate is my training data?
- Do I have frame drops?
- Do I have enough training data?



Classic Algorithm



Challenges when dealing with multi source data



Various sources need to be synchronized and sorted accurate in time



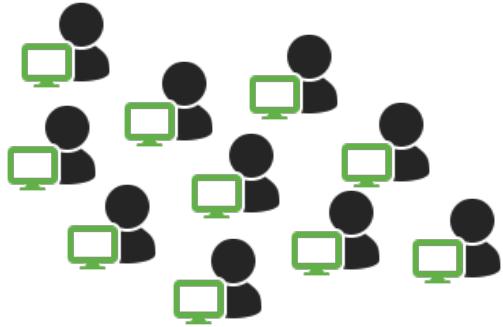
Data must not be lost.



Corrupt data have to be marked for analysis and data replay/simulation.

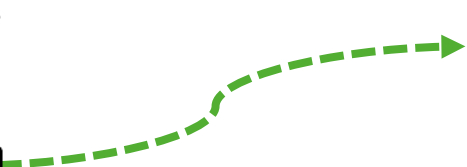
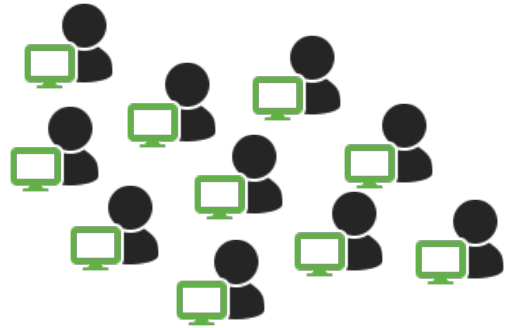


Software / Algo Development



ECU Software

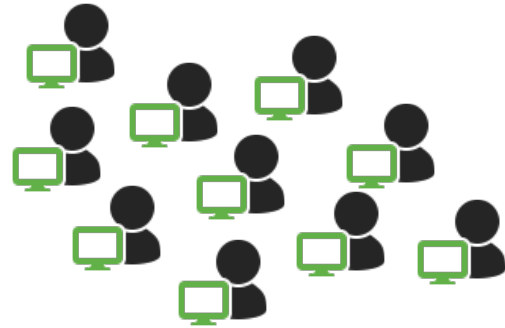
Software / Algo Development



Software / Algo Development

ECU Software

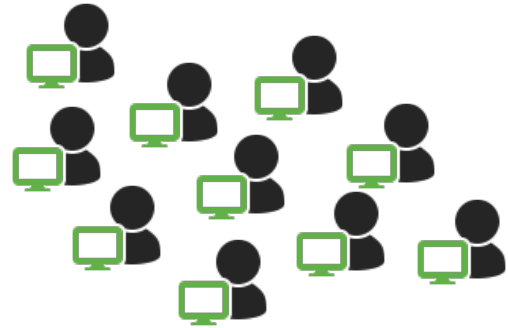
Test drives



Software / Algo Development

ECU Software

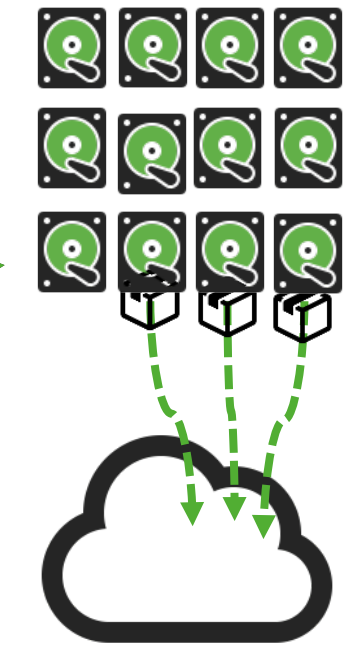
Test drives



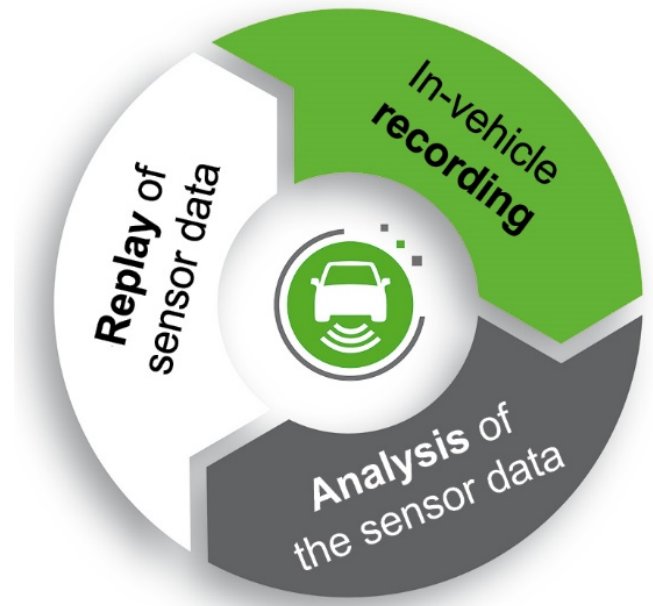
Software / Algo Development

ECU Software

Test drives



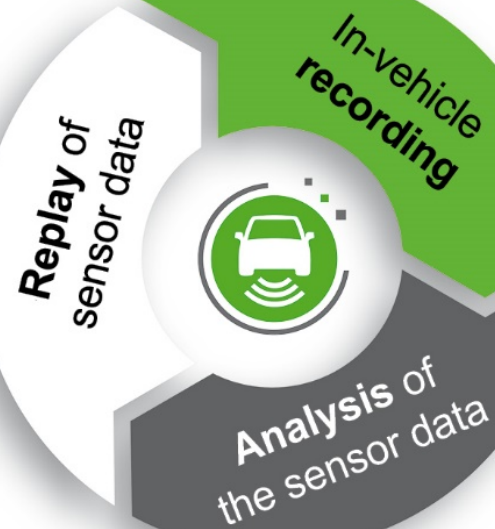
Connected Services



Software / Algo Development

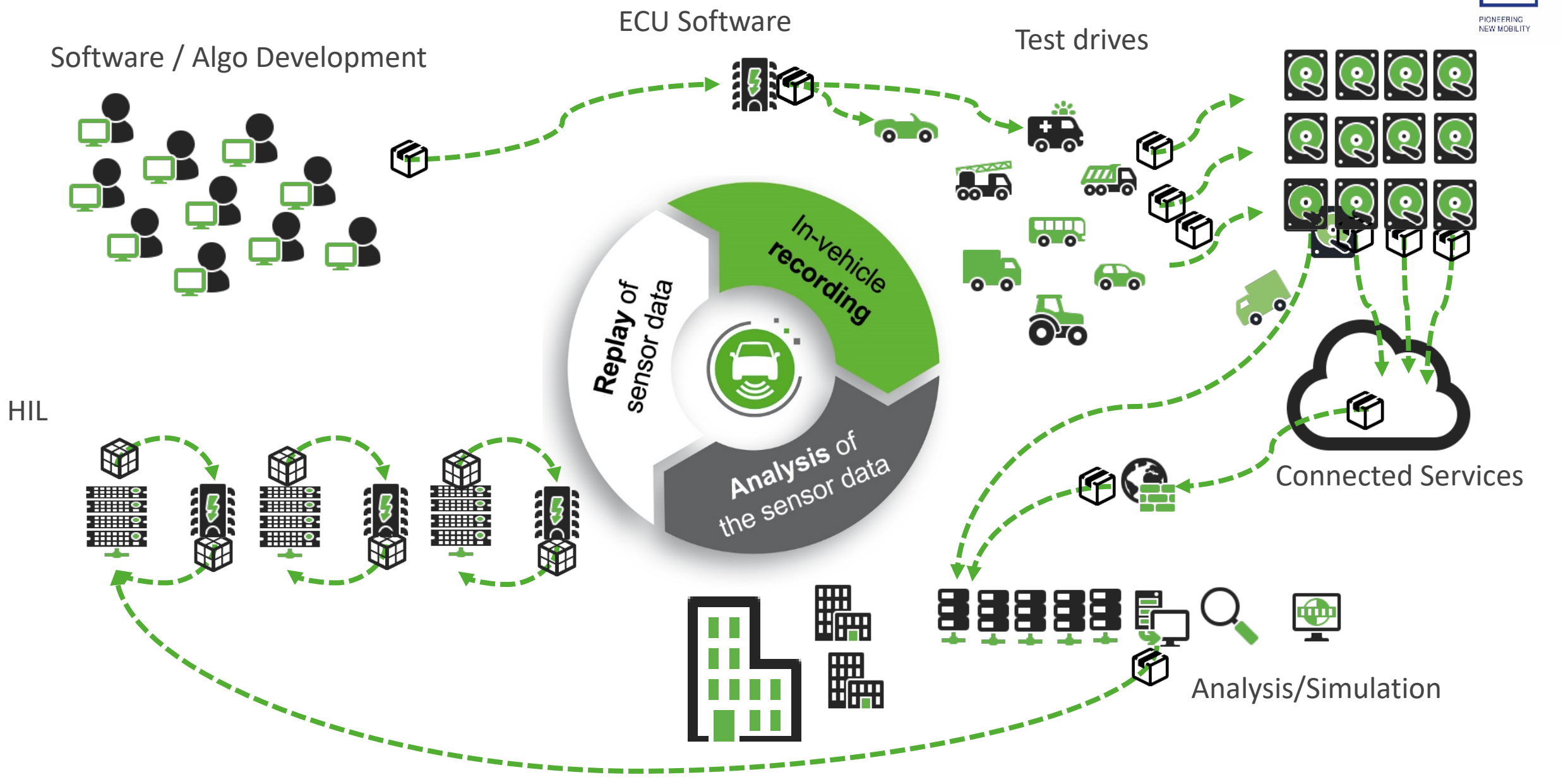
ECU Software

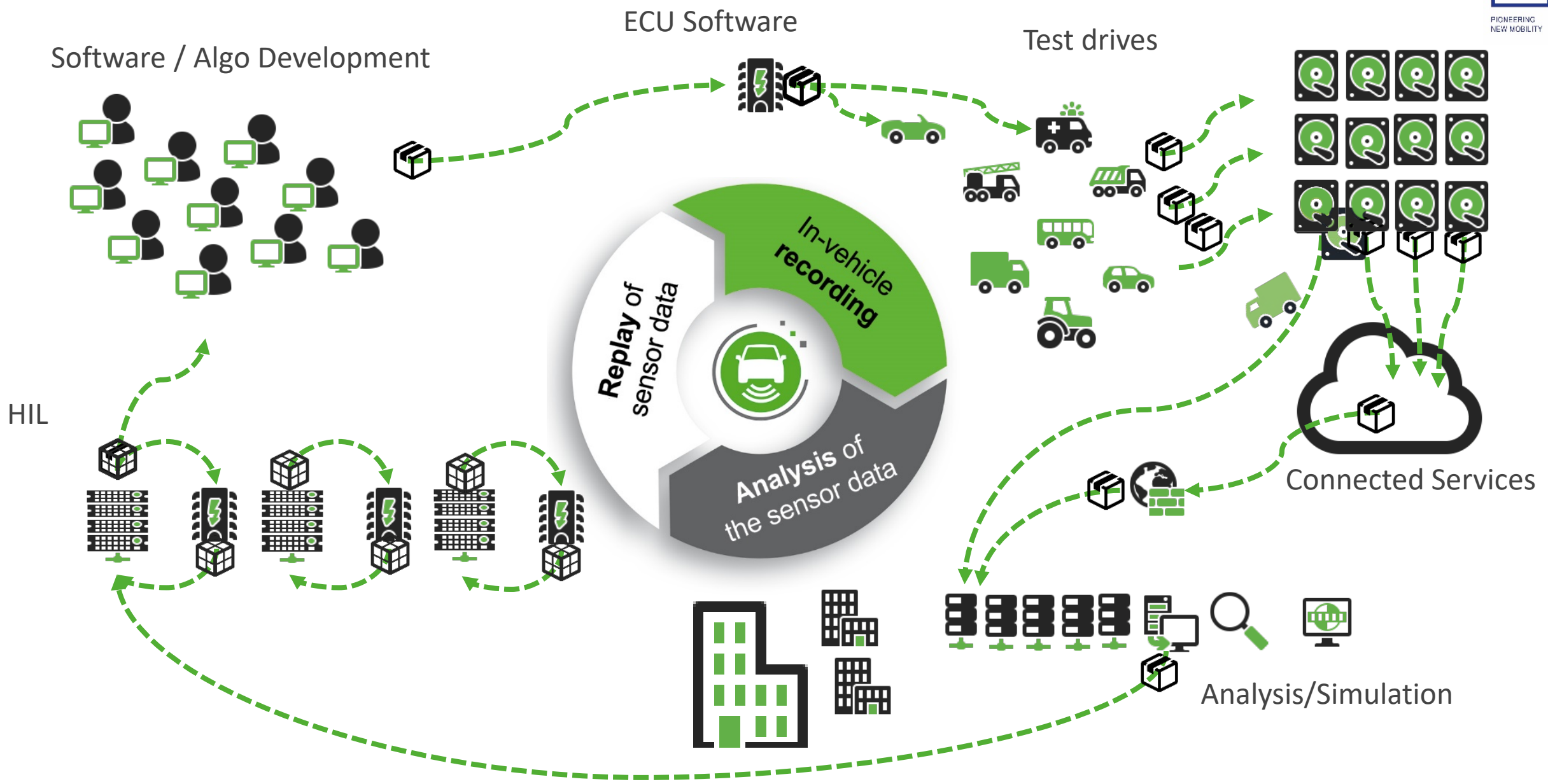
Test drives



Connected Services

Analysis/Simulation







Data recording

Test fleets collecting real environment test data



Data processing

Data quality assurance & enrichment



Data ingestion

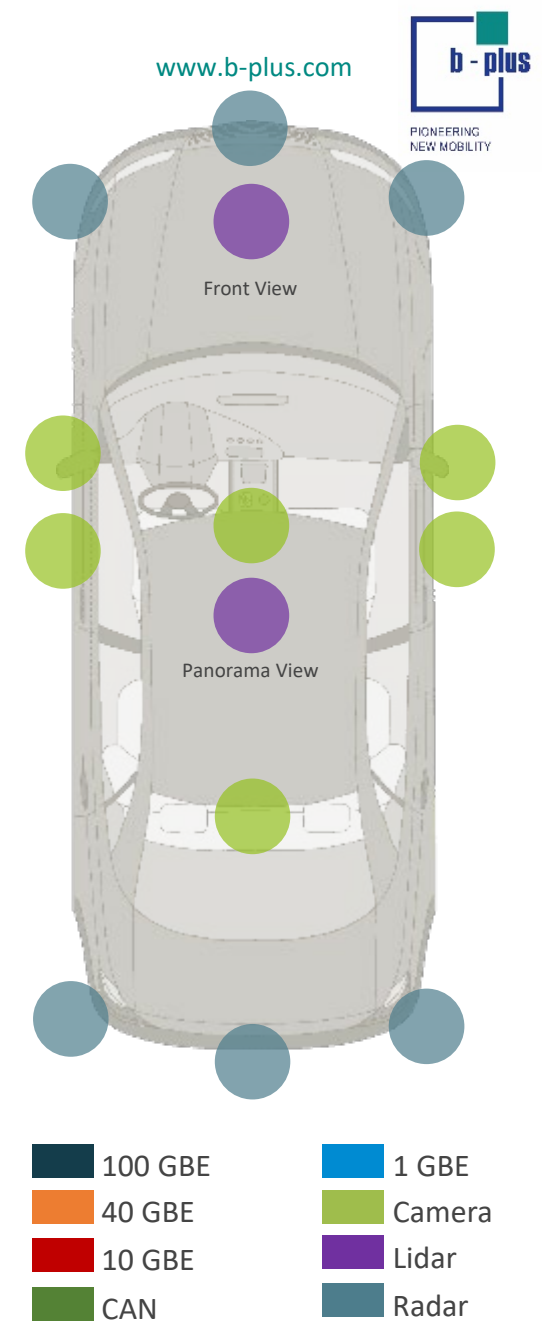
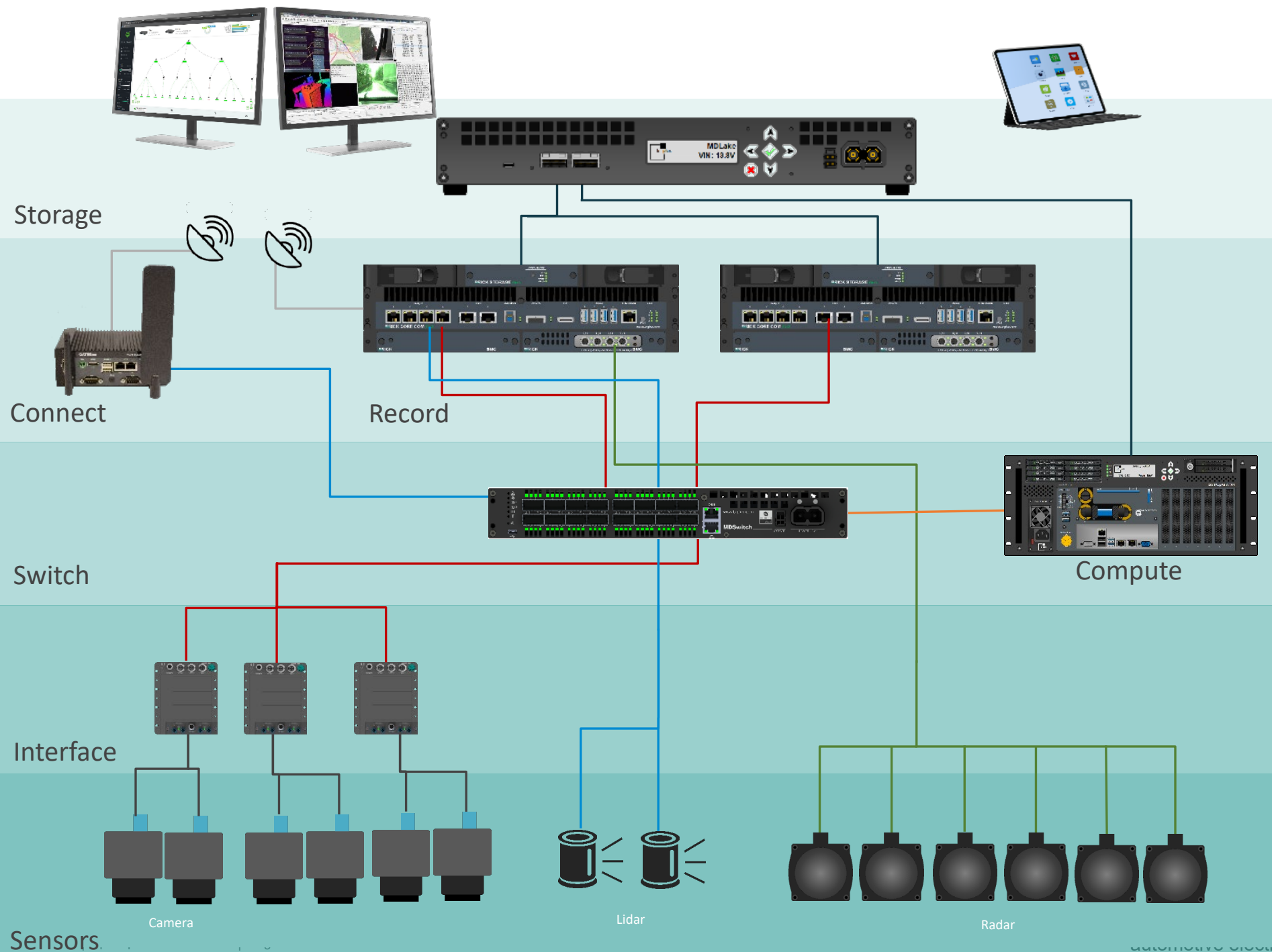
Upload into data center



- Data decoupling
- Chronological recording of all data sources
- Clock synchronization and time stamping
- Monitoring of data integrity

- Analytics / Scene detection
- Data enrichment
- Automated Labeling
- Live Processing

- Data transfer from test cars to data center
- Copies from various sources via copy station or storage unit
- Secure hash support



- | | |
|---|--|
| 100 GBE | 1 GBE |
| 40 GBE | Camera |
| 10 GBE | Lidar |
| CAN | Radar |

DATAlynx ATX4 Car Server



- Latest Server grade CPUs (AMD EPYC™ Processors or Intel® Xeon® Scalable Processors) (up to 2 CPUs)
- Liquid cooled processors and power supply (external cooling option)
- 6 – 32V DC automotive PSU with Ignition
- Up to 768GB DDR4-2933 ECC RDIMM
- Up to 80TB SSD space
- 7 PCIe Slots
 - Tailor made configurations
 - up to 2 NVIDIA Tesla cards
- Support for Multi-CPU/GPU configurations
- Add-ons for up to 4 GPUs
- -10°C to +60°C full operating



Mobile Datacenter Switch / MDSwitch



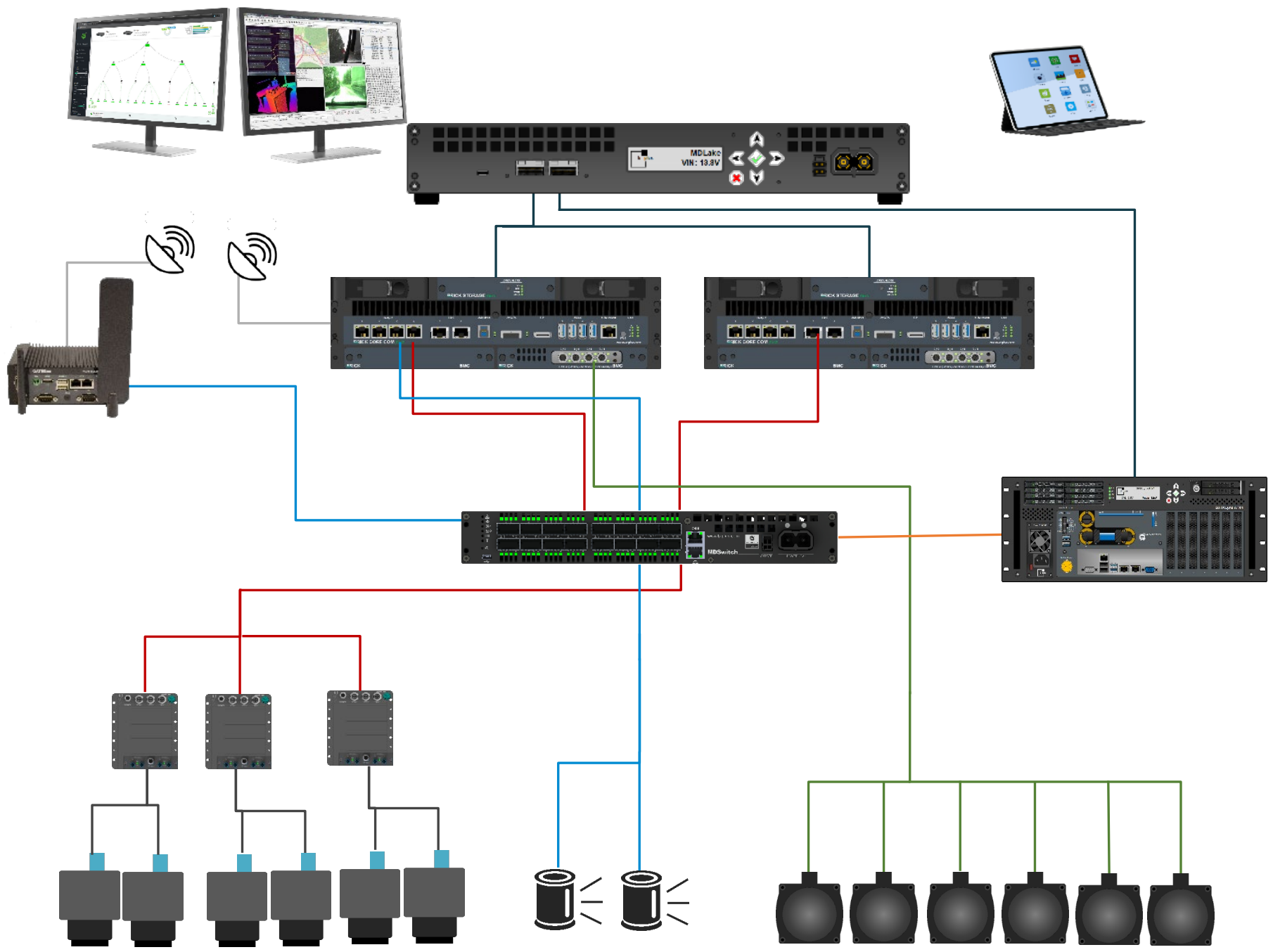
- Automotive Timesync Switch with IEEE 1588 802.1AS
- 16x 100GbE e.g. for upstream to Mobile Data Lake
 - Or 32x 50GbE
 - Or 64x 25GbE/10GbE
- Configuration via Website and Remote Update (Firmware and Config)
- Automotive power supply
- 16x QSFP28 interfaces for Fibre or Twinax cables

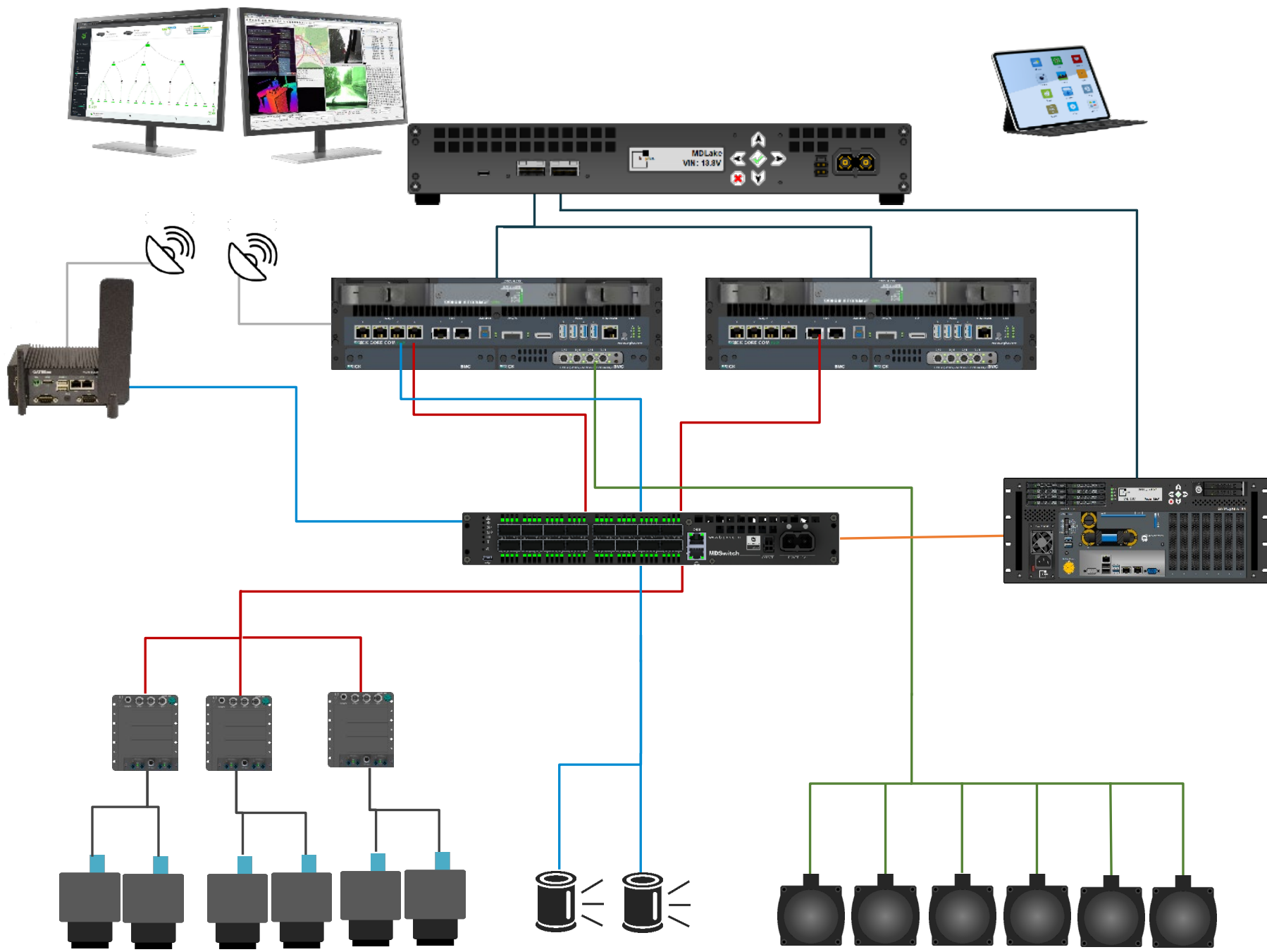


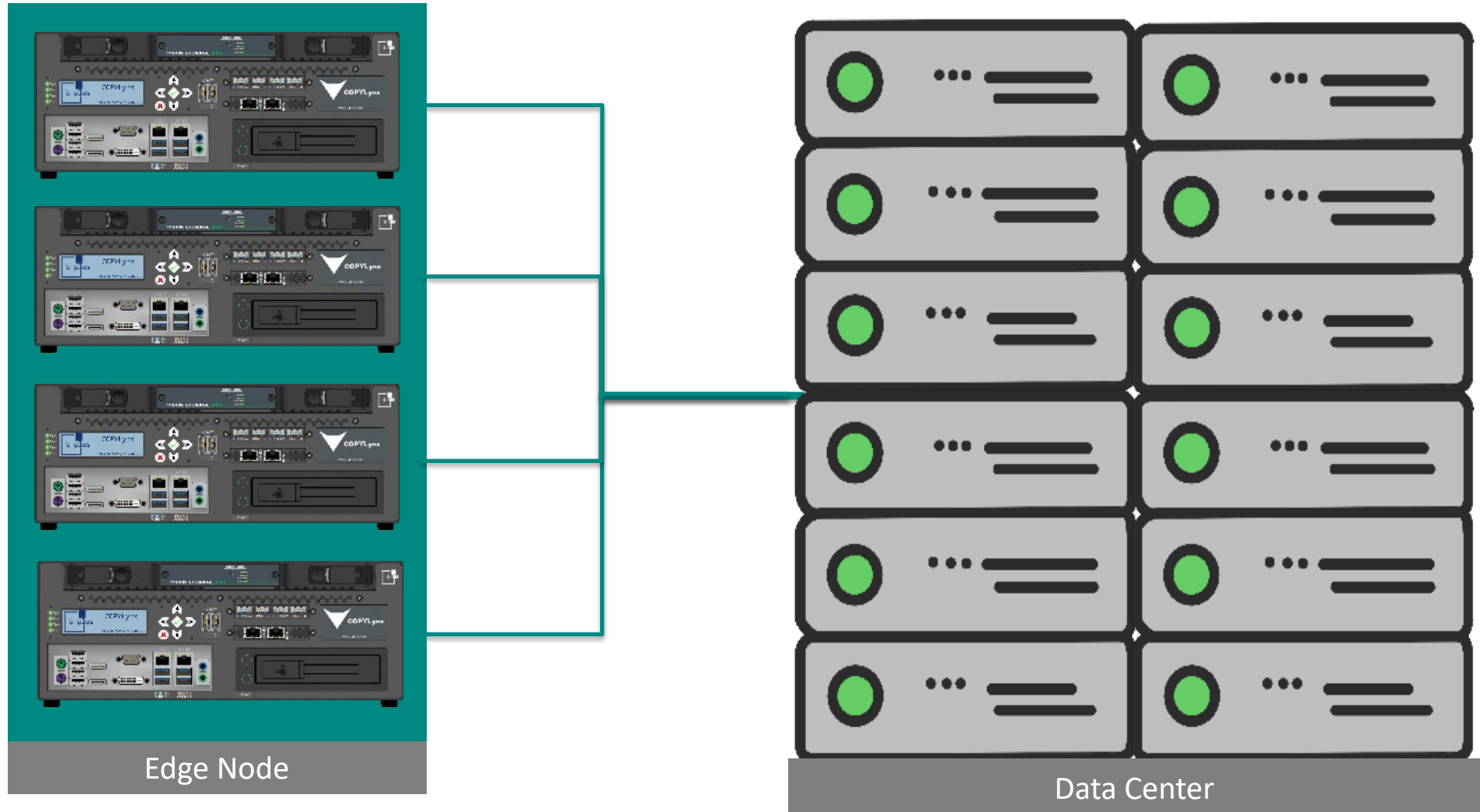
Mobile Data Lake / MDLake

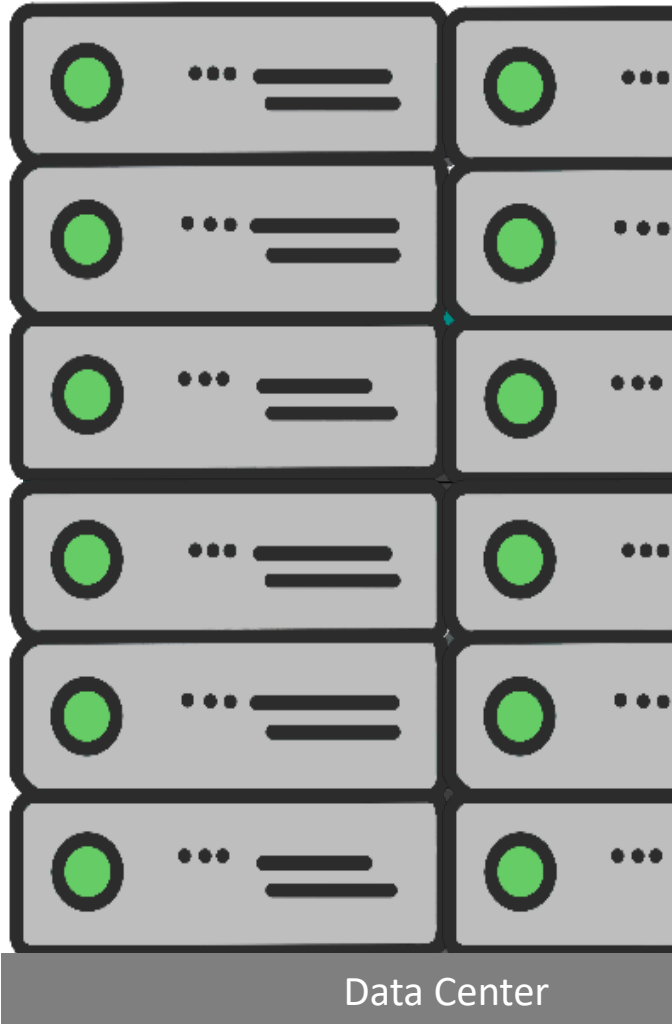
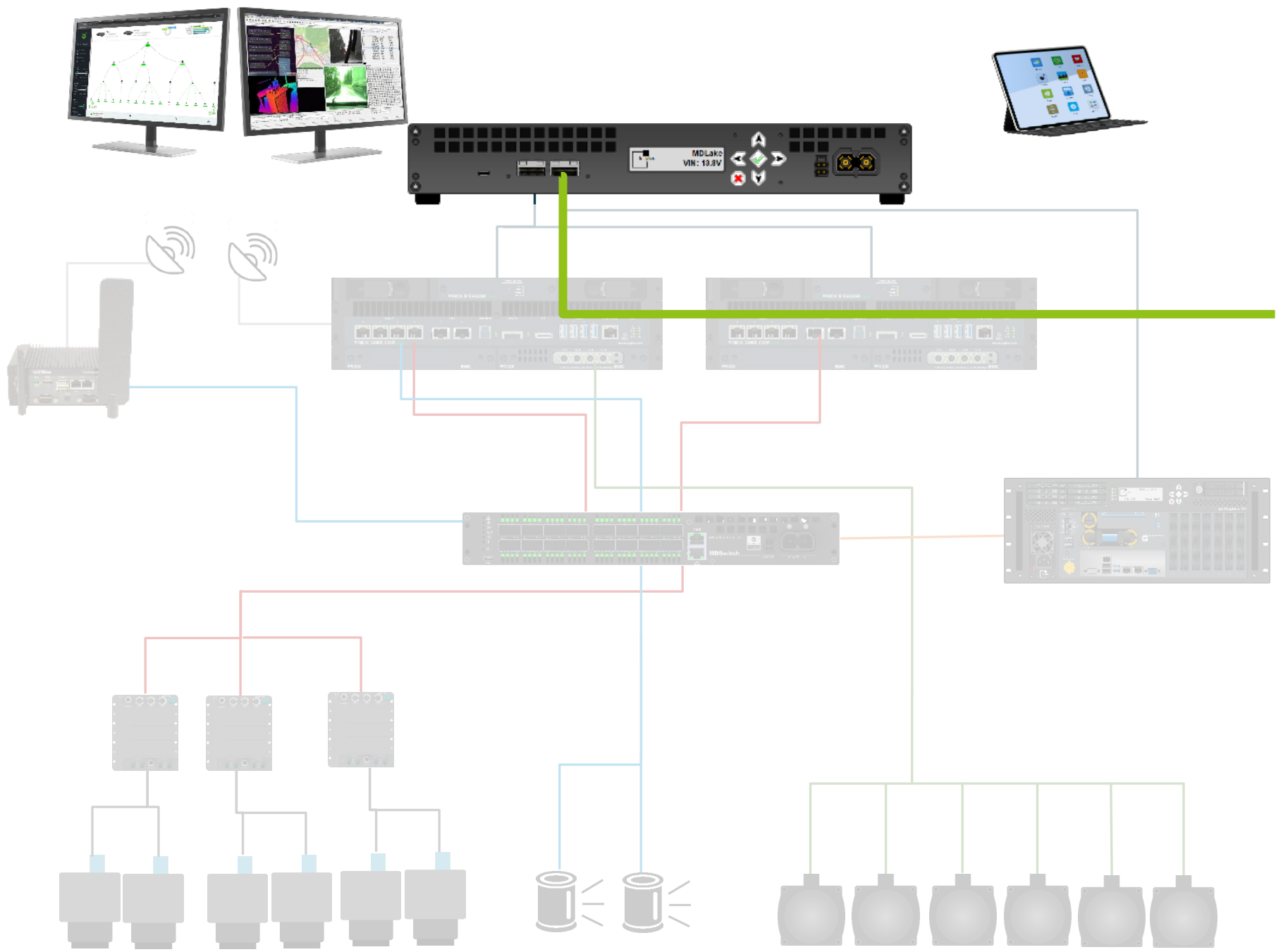


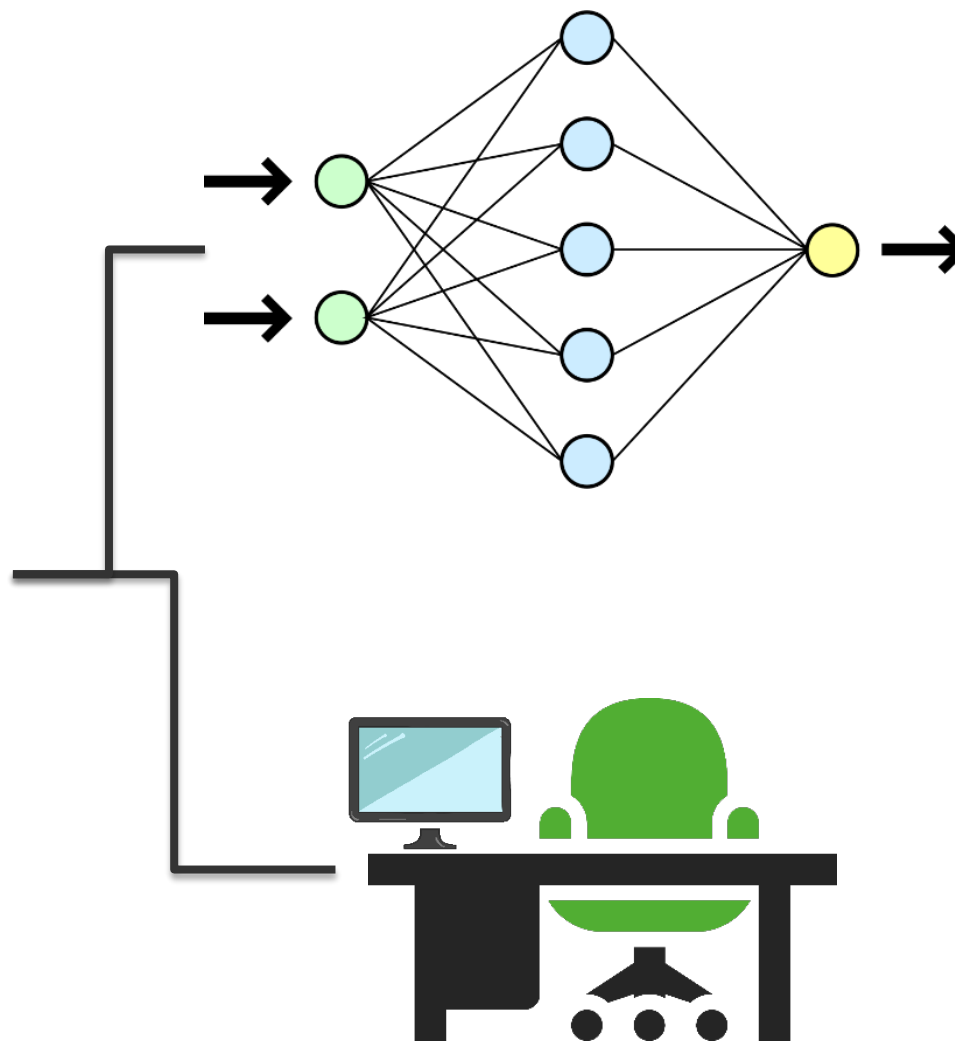
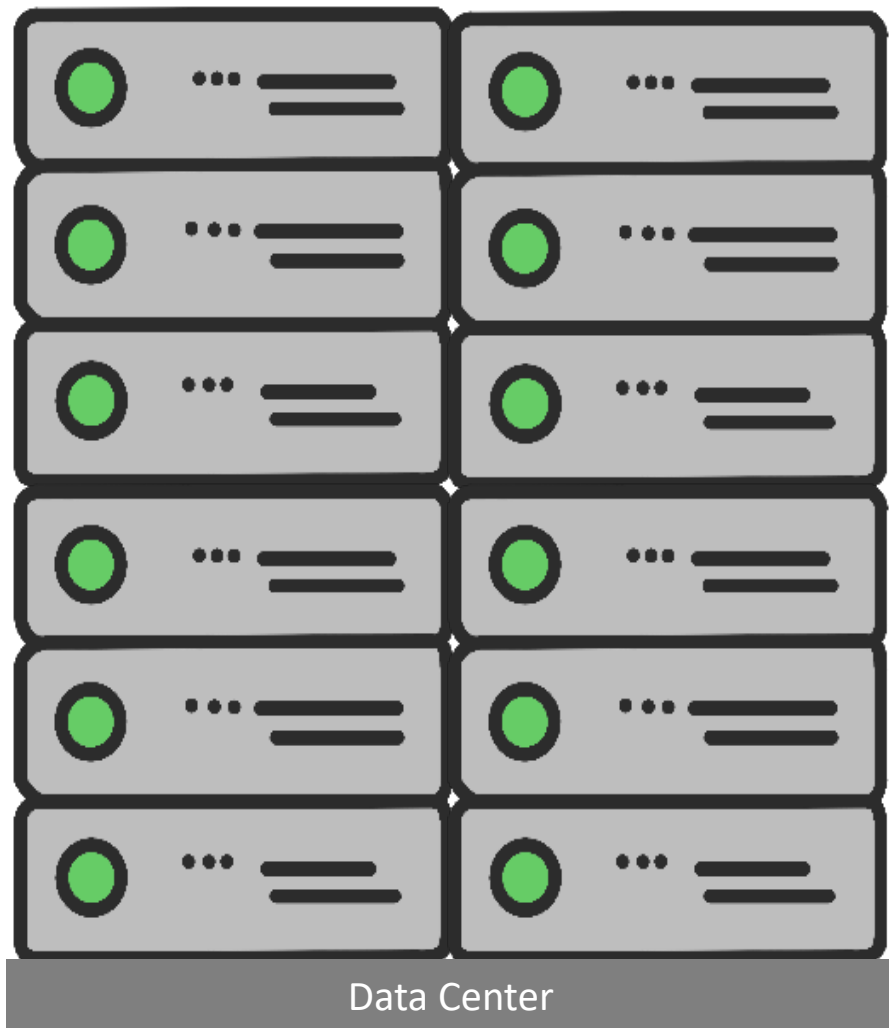
- Automotive DataLake System
- 16-Core ARM SoC with 16GB DDR4 and PCIe Gen4 Switch
- 16 NVMe SSDs connected via PCIe 3.0/4.0 x2
- Enables a 30TB to 180TB Storage JBOF
- 2x 100GbE QSFP28 Ethernet interfaces
- Low latency and highest throughput with RDMA technology
- NVMe-oF PCIe interface for Linux and Win for any Recorder
- 350W TDP, ~210W typical power consumption
- HxWxD: 44x320x380mm













PIONEERING
NEW MOBILITY



Alexander Noack

Head of Automotive Electronics bei b-
plus GmbH





Weka

- ▶ Shailesh Manjrekar
Head of AI and Strategic Alliances
www.weka.io



PREFERRED
SOLUTION
ADVISOR

Mobility-as-a-service with WEKA ai

Shailesh Manjrekar,
Head of AI and Strategic Alliances

Agenda

- Mobility-as-a-service - MaaS, paradigm change!
- New Architecture - Edge to Core to Cloud
- New Approach - Fuel your Digital Transformation with Accelerated DataOps

“Data is the new source code”





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Mobility-as-a-service

**\$54B in 2019 to \$556B market by 2026 at 39% CAGR – Globe
News wire June 2019**

THE FUTURE OF TRANSPORTATION STACK

<p>SERVICES</p> <p>ROUTE PLANNING</p> <p>SPATIAL</p>	<p>PARKING</p>	<p>CAR HAILING + POOLING</p>	<p>OTHER: AFTERMARKET, REPAIR, RENTAL</p>	<p>SPECIALTY VEHICLES</p> <p>2-WHEELERS</p>
<p>SAFETY & SECURITY</p> <p>PHYSICAL CAR & DRIVER SAFETY + ACCIDENT DETECTION</p>	<p>EMOTION, FATIGUE & ALCOHOL DETECTION + DISTRACTION AVOIDANCE</p>	<p>CYBERSECURITY</p>	<p>INTRUSION, TRACKING & RECOVERY</p>	<p>PUBLIC TRANSPORT</p>
<p>IN-CAR INTELLIGENCE + ASSISTANCE</p> <p>VEHICLE DIAGNOSTICS & PREDICTIVE MAINTENANCE + SENSOR-BASED VEHICLE SAFETY</p>	<p>PASSENGER-FOCUSED SENSORS (INCLUDING USAGE-BASED INSURANCE)</p>	<p>INFOTAINMENT + DISPLAY</p>	<p>PERSONAL / VOICE ASSISTANCE</p>	<p>TRUCKS / FREIGHT</p>
<p>AUTONOMY</p> <p>AUTOMATION SYSTEM</p>	<p>MAPPING, SIMULATION, & IMAGE RECOGNITION / ANNOTATION</p>	<p>AUTONOMOUS VEHICLE MAKER + TOOLS</p>	<p>FLIGHT</p>	
<p>INFRASTRUCTURE + CONNECTED CAR</p> <p>SENSOR NETWORKING INFRASTRUCTURE (V2V, V2X) - LPWA, CELLULAR, WIFI</p>	<p>CONNECTED CAR - DATA, PLATFORM, SOFTWARE</p>	<p>FLEET + TRAFFIC MANAGEMENT</p>	<p>OTA CAR SOFTWARE UPDATE + SMART PHONE ENABLED TELEMATICS</p>	<p>OTHER: HYPERLOOP, PERSONAL MOBILITY</p>
<p>INTELLIGENT MANUFACTURING</p> <p>NEW/ADVANCED MATERIALS</p>	<p>RAPID PROTOTYPING - 3D PRINTING, MODULARIZATION, OPEN SOURCE</p>	<p>ADVANCED / AUTOMATED ASSEMBLY LINE</p>	<p>MATERIAL CHARACTERIZATION & TESTING</p>	
<p>ONBOARD SENSORS</p> <p>LOCATION - GIS, PRECISION POSITIONING, PATH PLANNING</p>	<p>VISION / CAMERA</p>	<p>LIDAR</p>	<p>RADAR</p>	

WeksFS powers Mobility-as-a-service stack

SERVICES

- WE-ride

SAFETY & SECURITY

IN-CAR INTELLIGENCE + ASSISTANCE

- (Telematics)

AUTONOMY

- tuSimple, largest electric car company, autonomous trucks in EMEA

INFRASTRUCTURE + CONNECTED CAR

- Cerence - AI, for World in Motion

INTELLIGENT MANUFACTURING

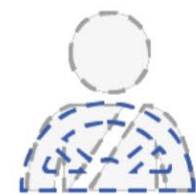
ONBOARD SENSORS

- Innovize

SAE (Society of automotive engineers) – Levels of automation

SOCIETY OF AUTOMOTIVE ENGINEERS (SAE) AUTOMATION LEVELS

Full Automation



0	1	2	3	4	5
No Automation	Driver Assistance	Partial Automation	Conditional Automation	High Automation	Full Automation
Zero autonomy; the driver performs all driving tasks.	Vehicle is controlled by the driver, but some driving assist features may be included in the vehicle design.	Vehicle has combined automated functions, like acceleration and steering, but the driver must remain engaged with the driving task and monitor the environment at all times.	Driver is a necessity, but is not required to monitor the environment. The driver must be ready to take control of the vehicle at all times with notice.	The vehicle is capable of performing all driving functions under certain conditions. The driver may have the option to control the vehicle.	The vehicle is capable of performing all driving functions under all conditions. The driver may have the option to control the vehicle.

Building AI for Autonomous vehicles is hard

Every neural net needs to handle thousands of conditions and geo-locations

- Safety is a non compromisable primary objective
 - Models need to be tested on huge data-sets to be confident; needs performance for faster iterations
- Needs tons of data
 - Innumerable scenarios is the key to building good AV models
- Inference on the edge
 - Edge has limited hardware capabilities, hence ability to chose right model, with multiple, faster iterations and access to tons of data is key
- Reproducibility to understand why a model behaved certain way
 - Proper version control of datasets, models and experimentation

Data has become the new source code and timely access to tons of data is cornerstone for success of autonomous vehicles

Production grade AV platform functionality

Scalable AI
training

PB scale AI
testing

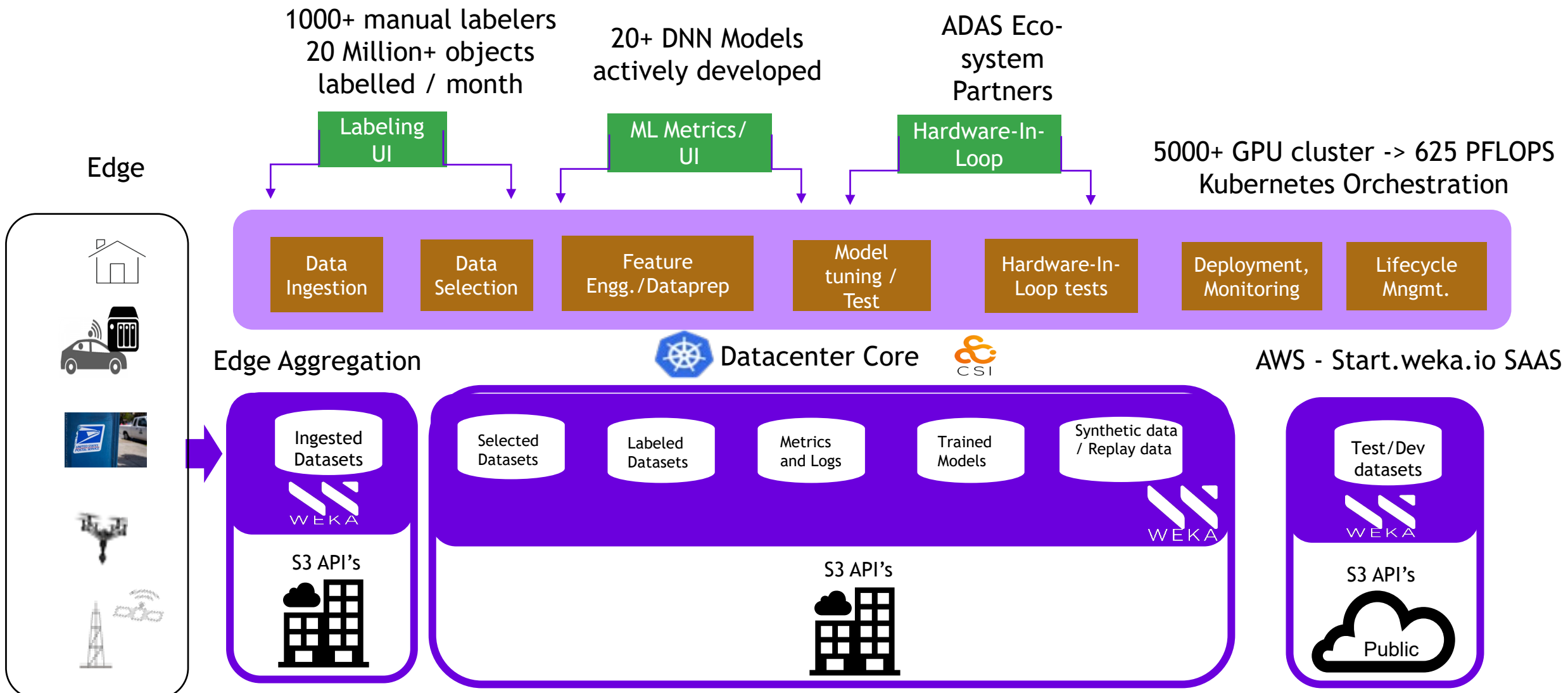
AI based data
selection and
mining

Traceability:
model ==
code + data

Seamless PB
scale data
access

Workflow
automation

Software Defined Car – Advanced Driver Assistance System (ADAS) data pipeline

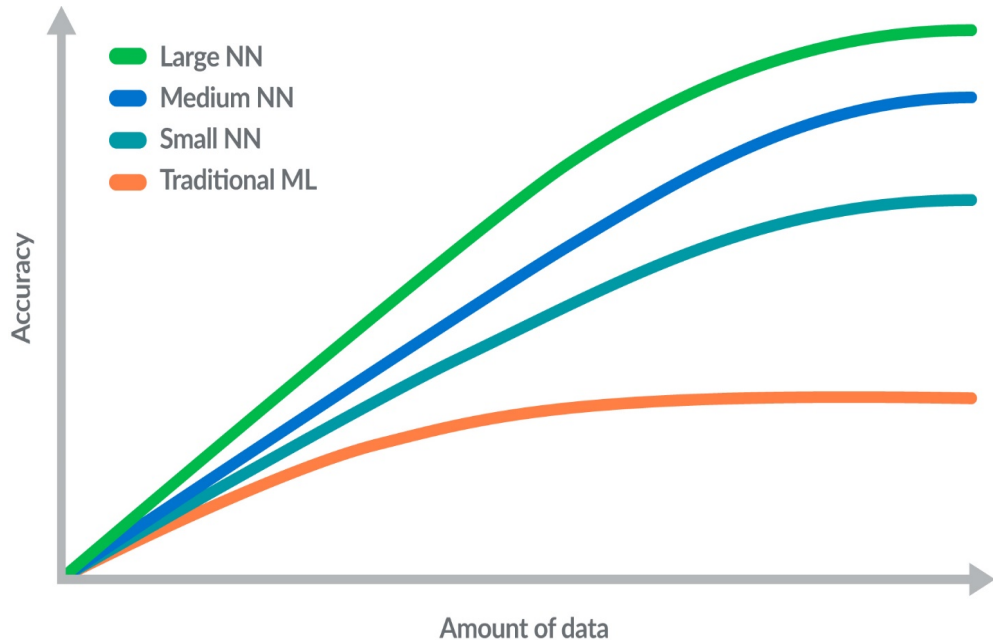


Deep Learning - Data Centric Use Cases

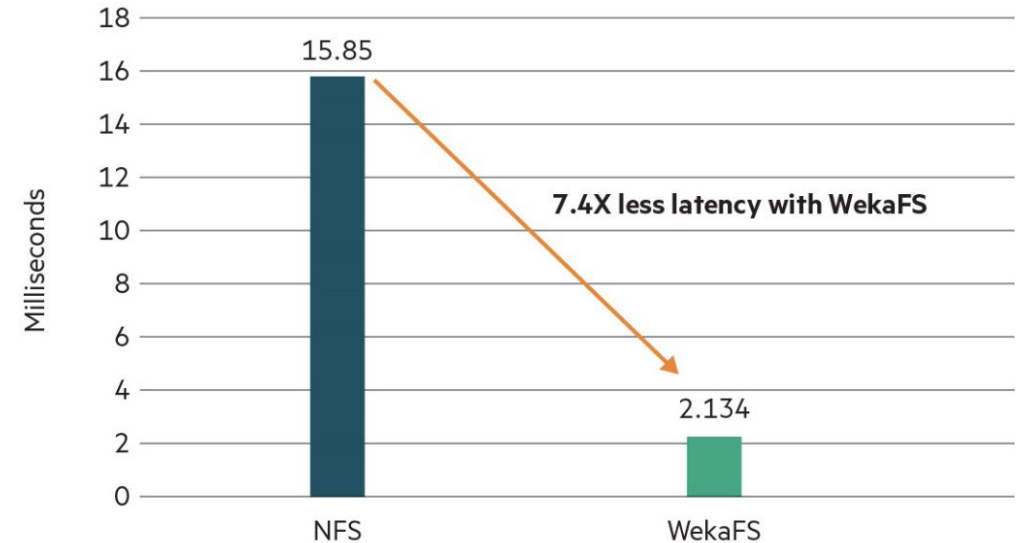
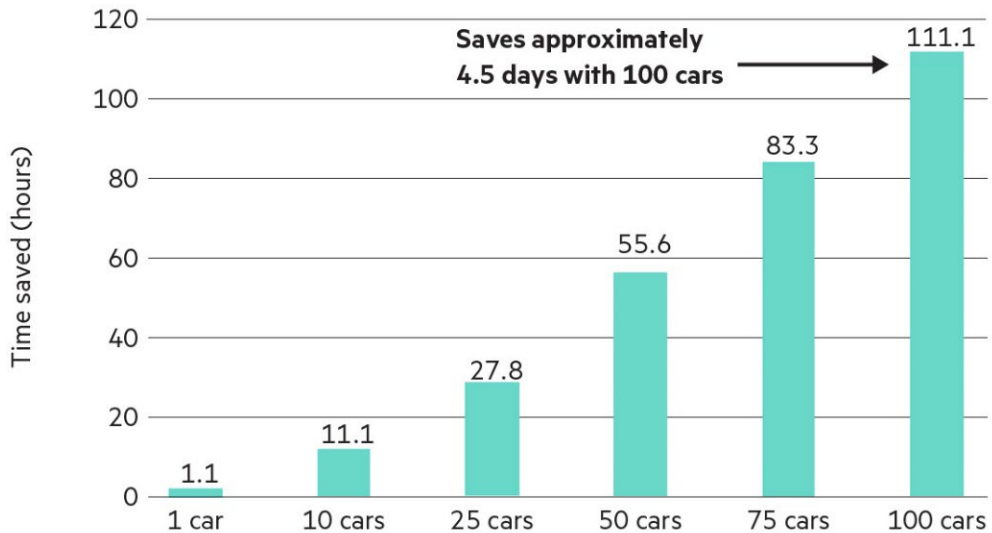
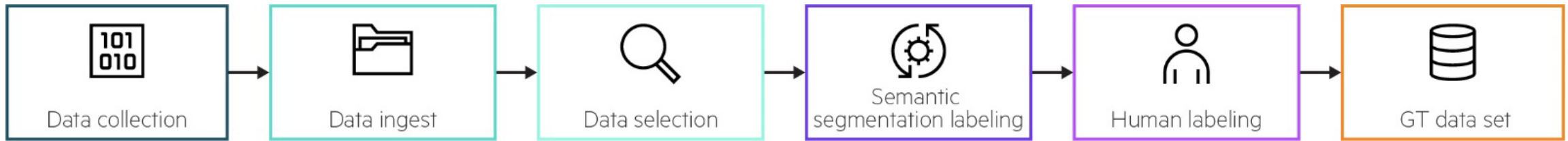
Advanced Driver Assist System (ADAS)



Level of Autonomy	Deep Neural Networks Needed	Survey Car	Data Storage	Data Processing
Level 2+	10	Equipped with 2MP Cameras	2 PB per Year per Car	100 GPU Servers per Car



Semantic segmentation – image classification at a pixel level – Ground Truth (Labeled Datasets)



228 GB of City scape dataset used on WekaFS, Apollo 6500 running ENET CNN for semantic segmentation
<https://www.weka.io/promo/2019-11-wp-hpe-storage-on-semantic-segmentation-2/>

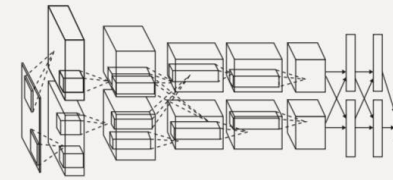
DNN's Becoming More Complex With Several Billion Hyperparameters

Use cases moving from Computer Vision to NLP/NLU and multi-modal

Advances in Deep Learning Methodologies:

- Deep Learning
- Transfer Learning
- Federated Learning
- Active Learning

Convolutional Networks



PReLU



PReLU



BatchNorm



Concat

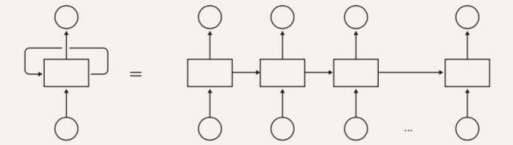


Dropout



Pooling

Recurrent Networks



LSTM



GRU



Highway



Projection

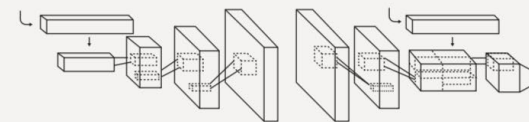


Embedding

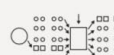


BiDirectional

Generative Adversarial Networks



3D-GAN



Rank GAN



Conditional GAN



Coupled GAN

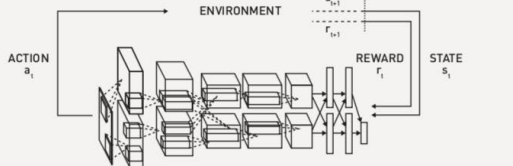


Speech Enhancement GAN

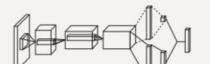


Latent Space GAN

Reinforcement Learning




DQN



Dueling DQN

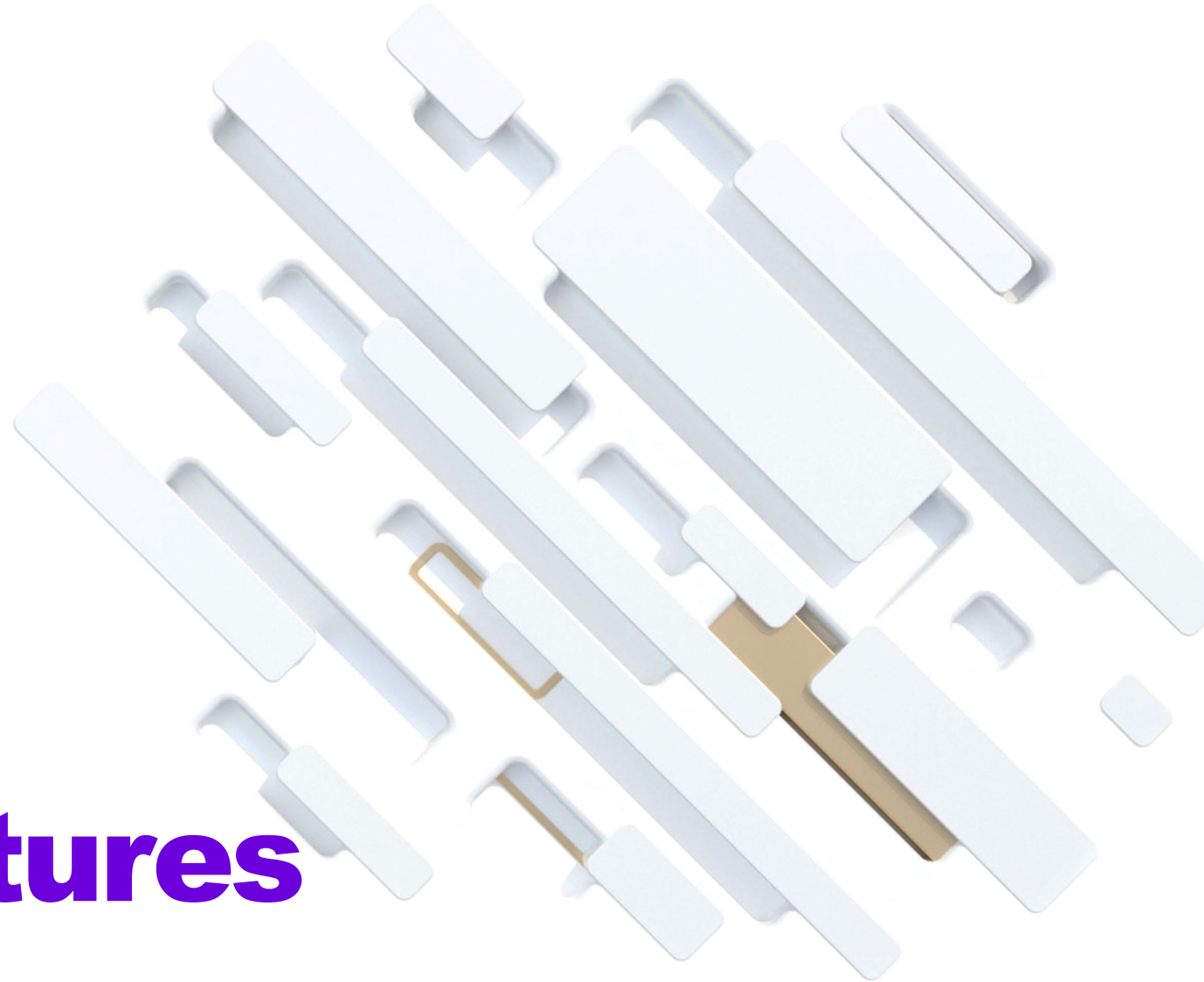


A3C



0

2



New Architectures

GPUs Have “Densified” Compute into a Single Server Creating a Huge Data Bottleneck



100x More Compute
40x more network



GPU Accelerated Server

Current NAS solutions
cannot feed these
machines with enough
data

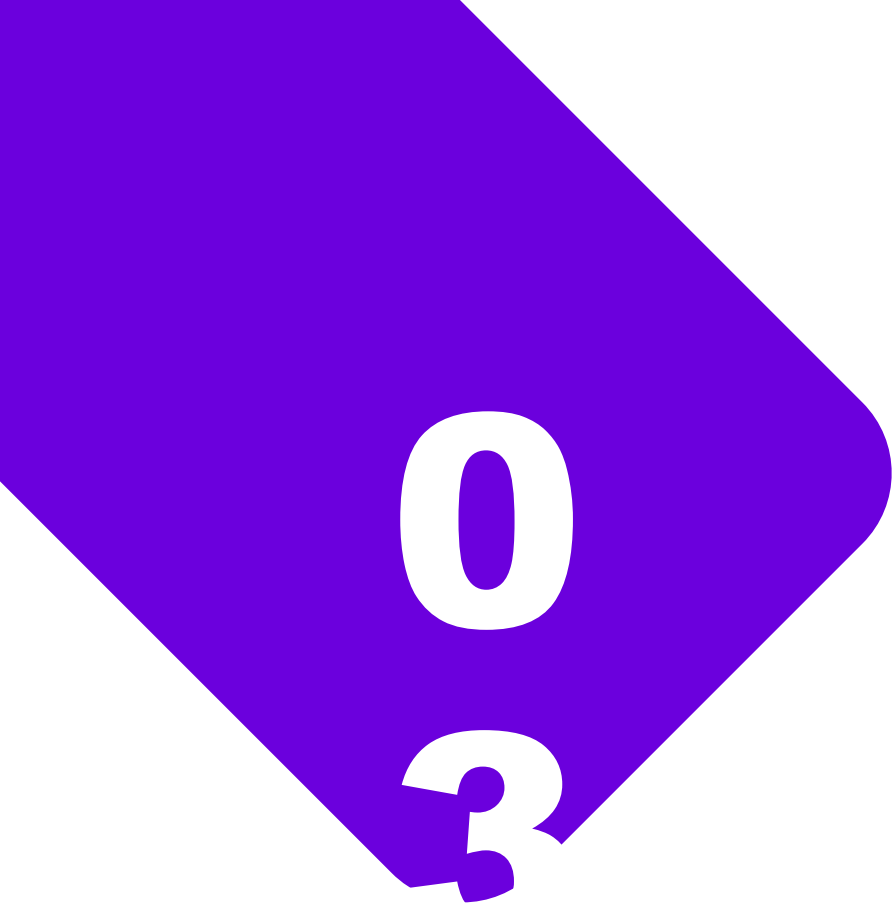
CPU-Only Servers

- 100's of servers with CPUs
- 100's of low bandwidth network connections
- No one server was particularly demanding on storage

Weka solves the last mile problem

Single storage substrate for the entire data pipeline

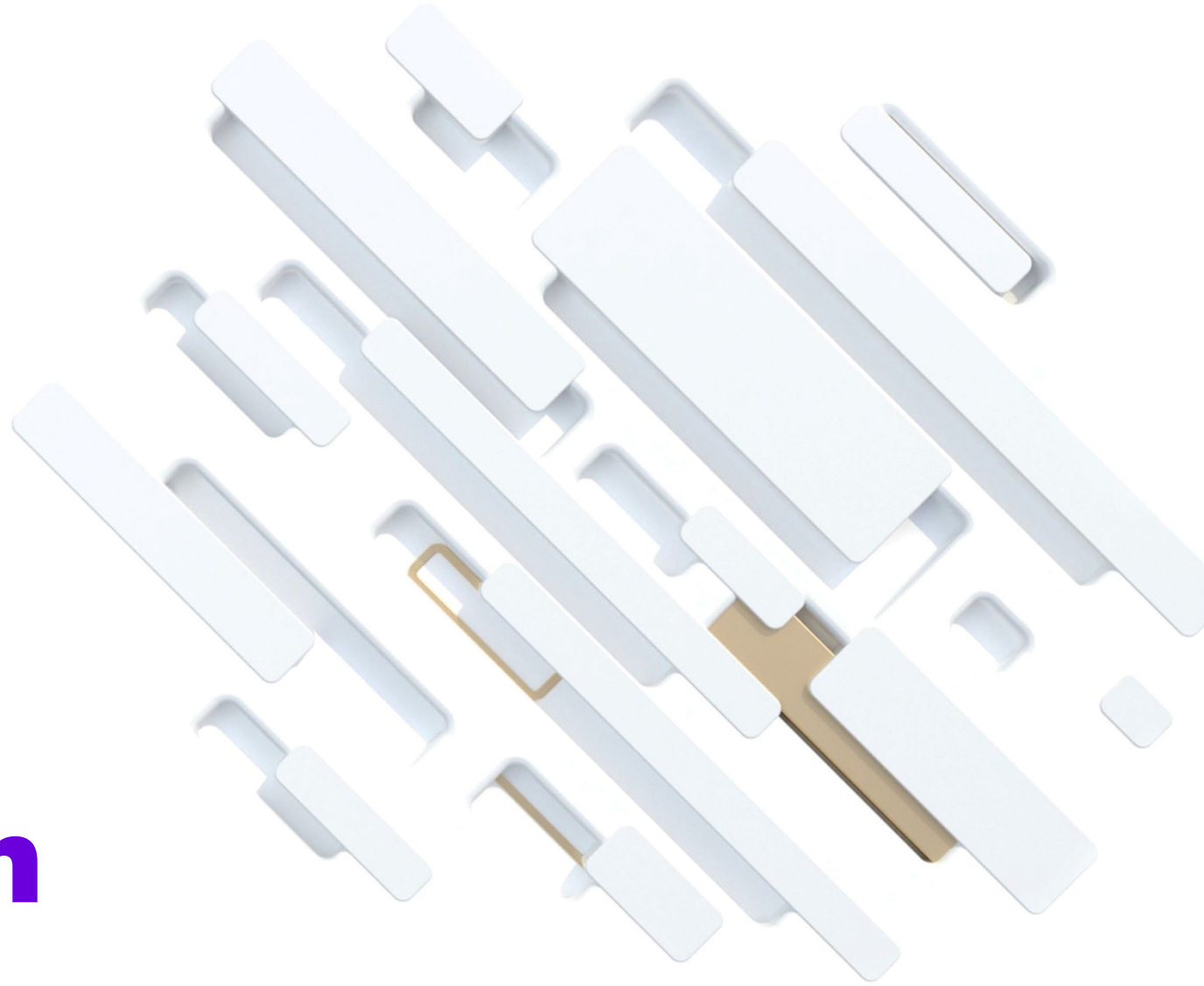




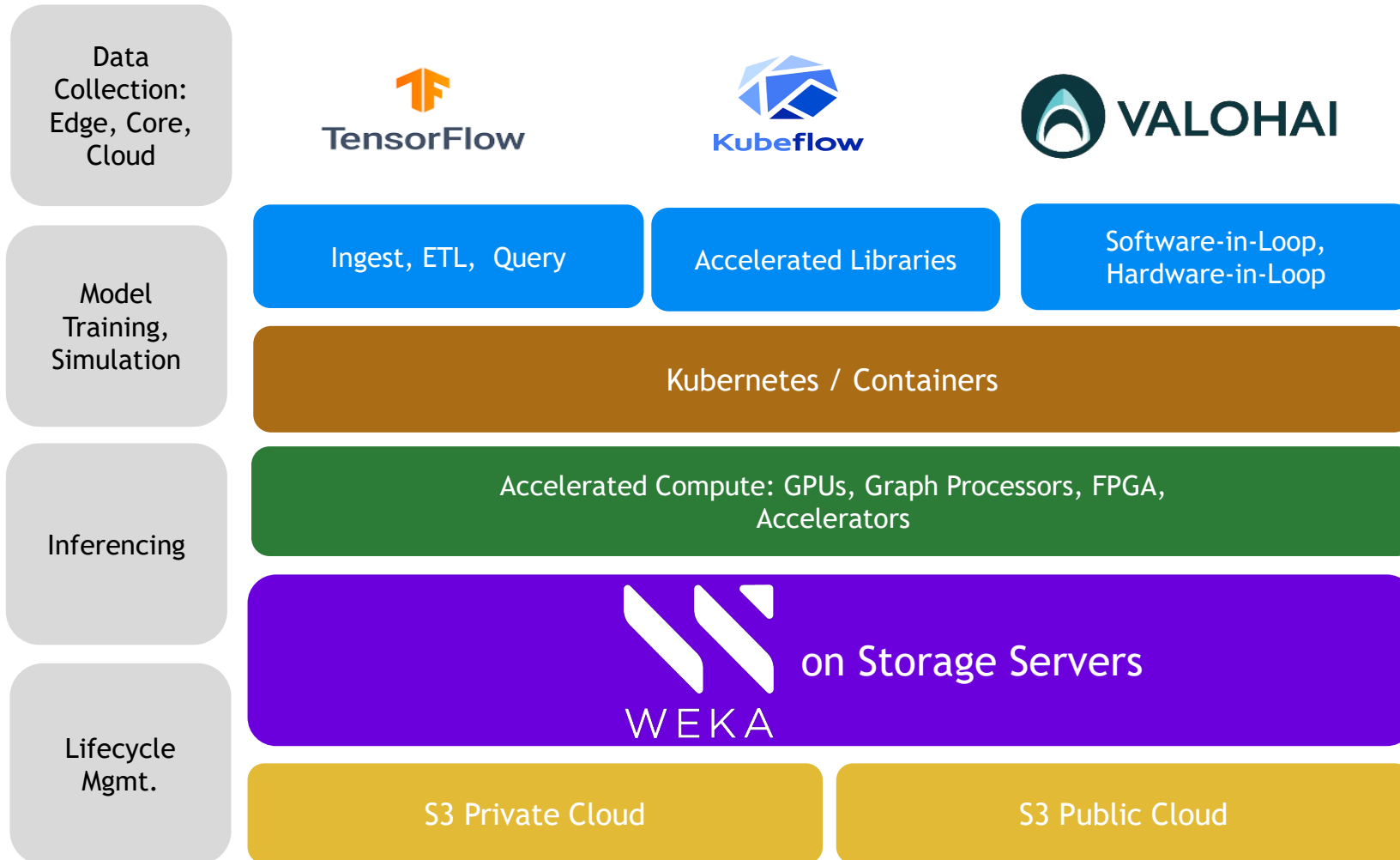
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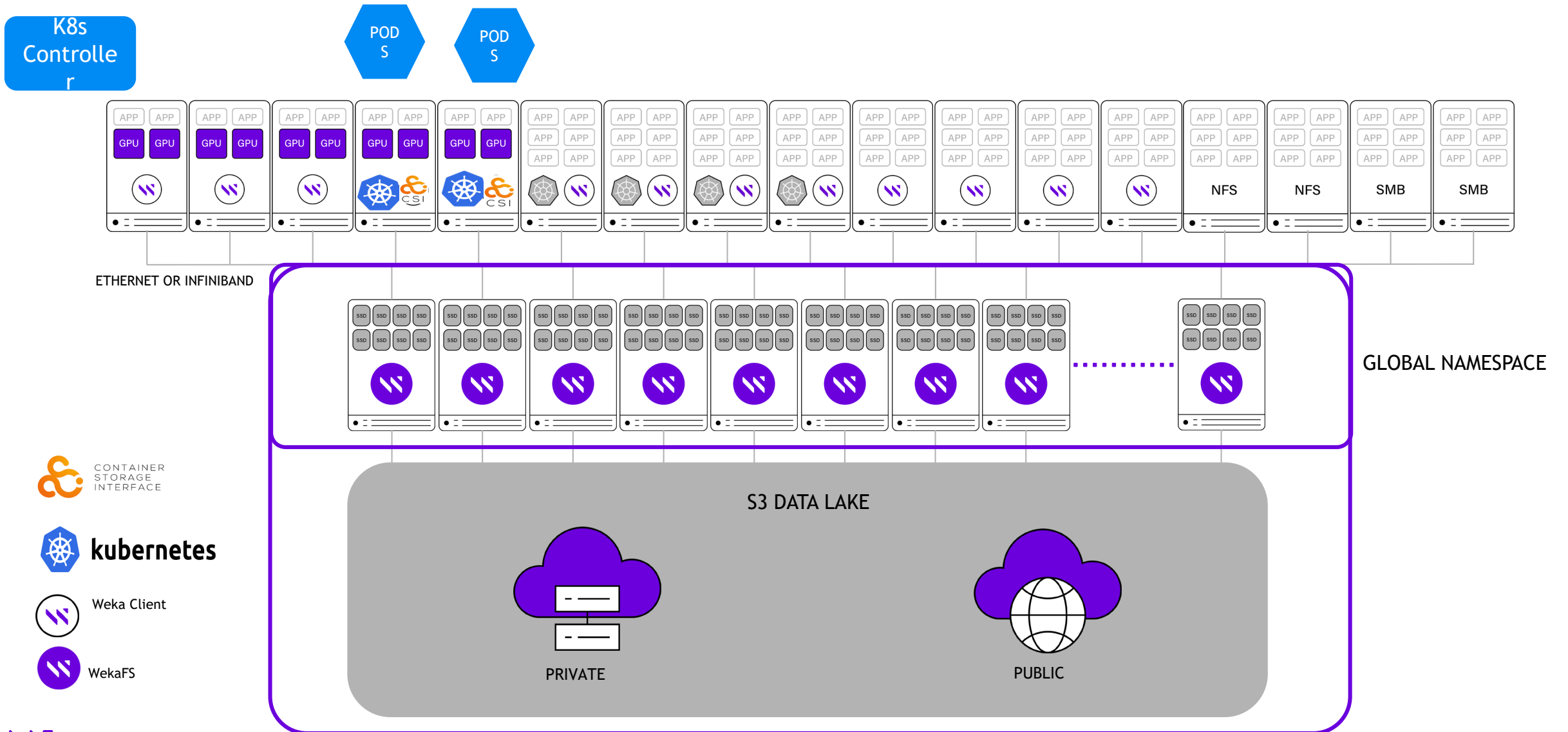
New Approach



WekaAI for Accelerated DataOps – Small / Medium / Large Bundles

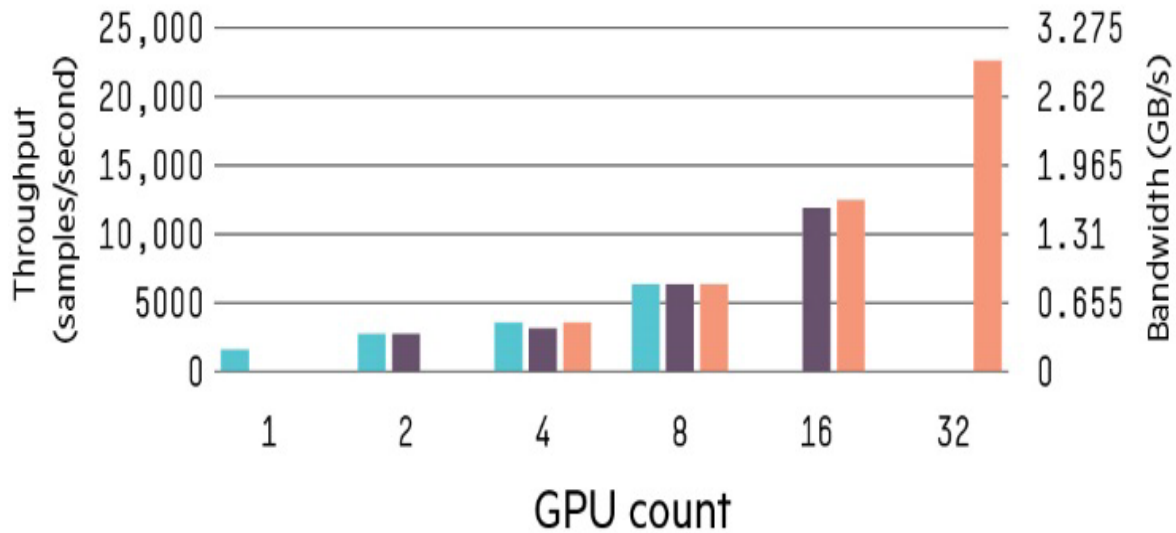


Weka AI deployment

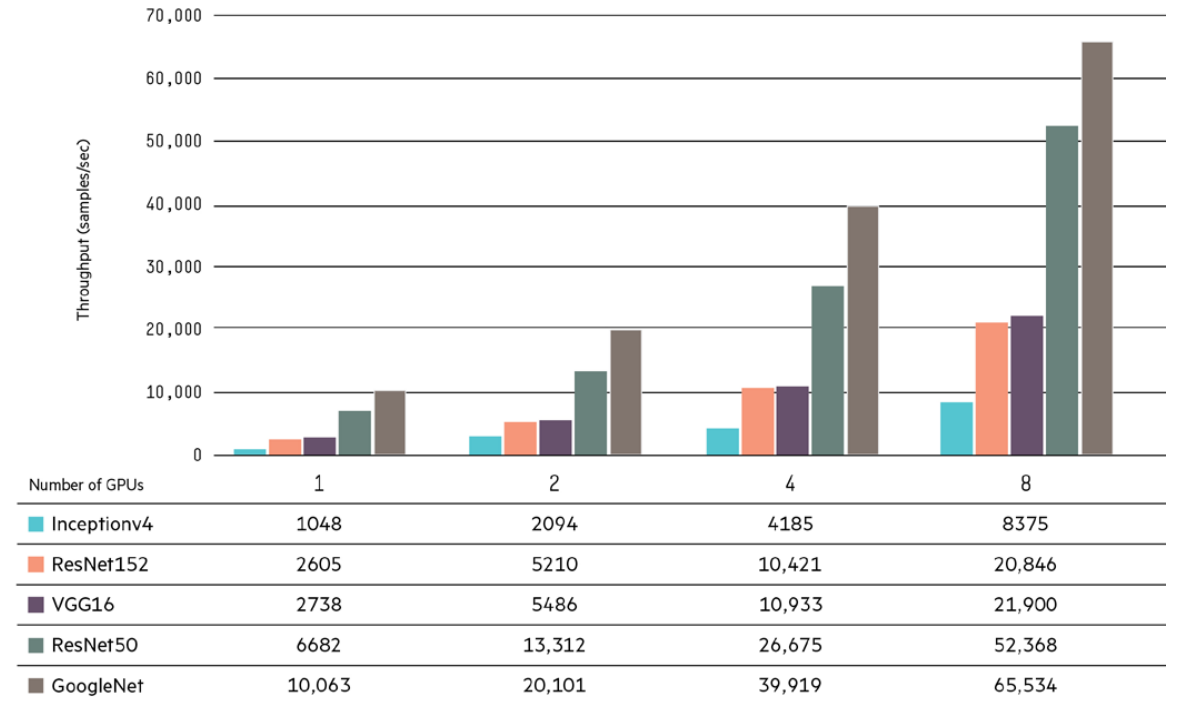


Weka AI, 4 HPE GPU servers - Training and Inference samples/sec

ResNet50 Synthetic Training

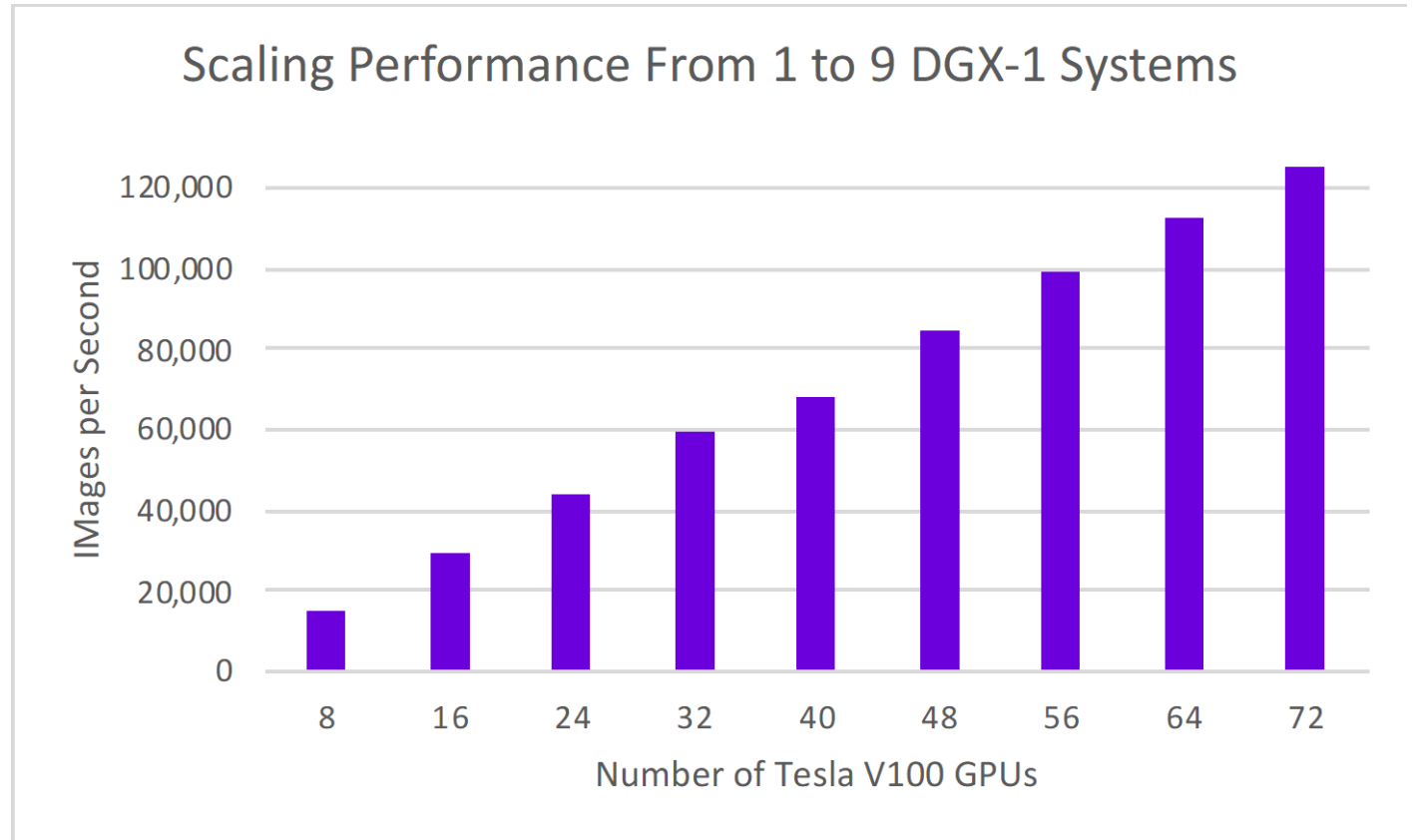
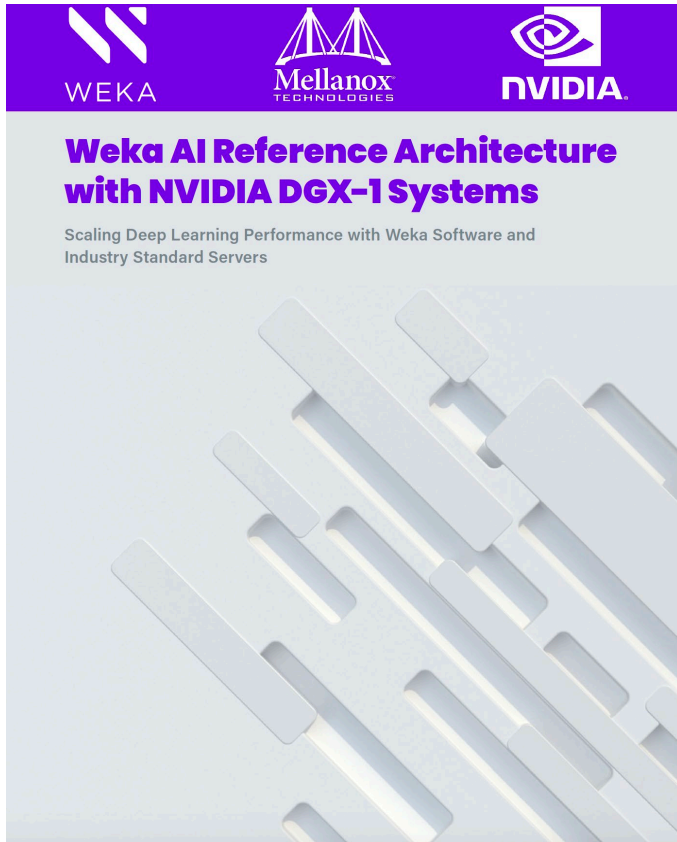


WekaIO Inference Throughput by GPU



Imagenet dataset used TFRRecord on WekaFS, 4x Apollo 6500 running Resnet50 CNN for training and inference. Horovod and NCCL used for intercommunication <https://www.weka.io/wp-content/uploads/files/2020/04/HPE-accelerate-performance-for-production-ai-tech-whitepaper-1.pdf>

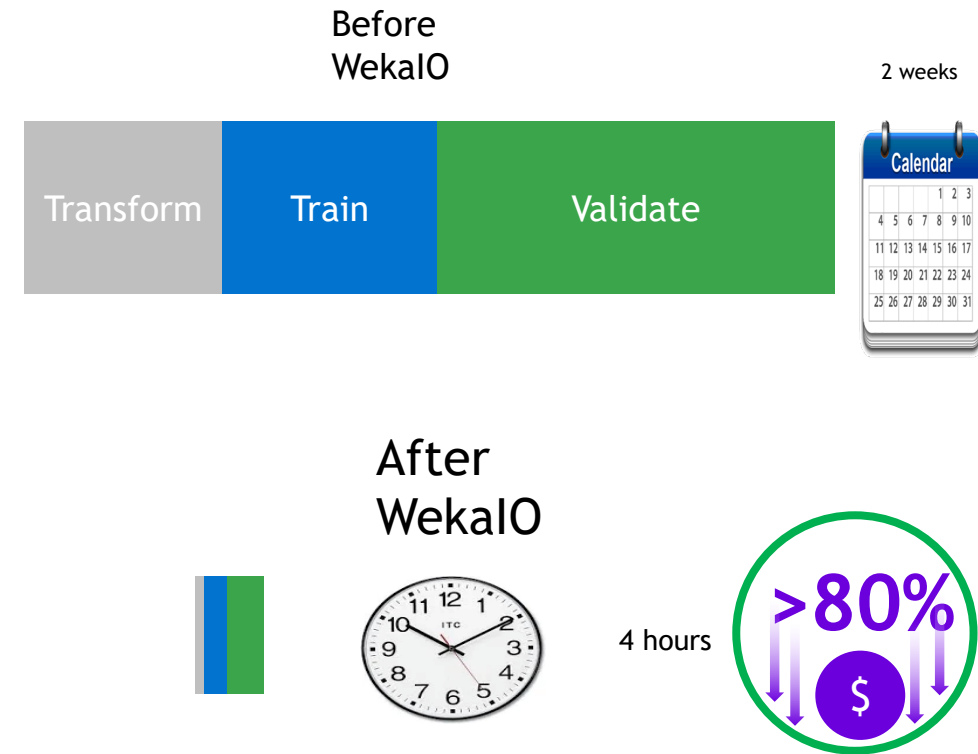
Weka AI Reference Architecture



- Fully saturate 100Gbit Network link
- 3x faster than local drive Storage
- 10x faster than all flash NAS
- Perfect linear scaling as cluster expands

Weka AI for Data Scientists, CDO's and CAO's

- Improve productivity and faster time to market and value
 - accelerate large scale data pipelines with reduced epoch times, fastest inferencing and highest images / secs benchmarks
 - run entire pipeline on the same storage backend
 - Faster than local storage

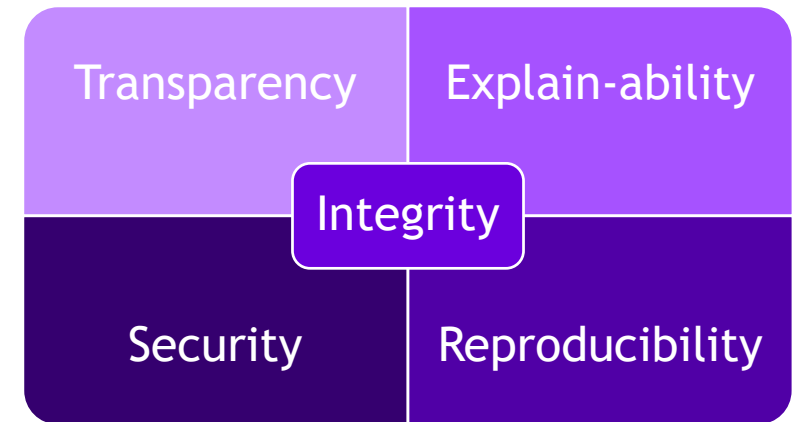


30% better utilization results into \$1.13M in savings for 10 node GPU cluster with 3 Data scientists, over 3 years

Weka AI for Data scientists

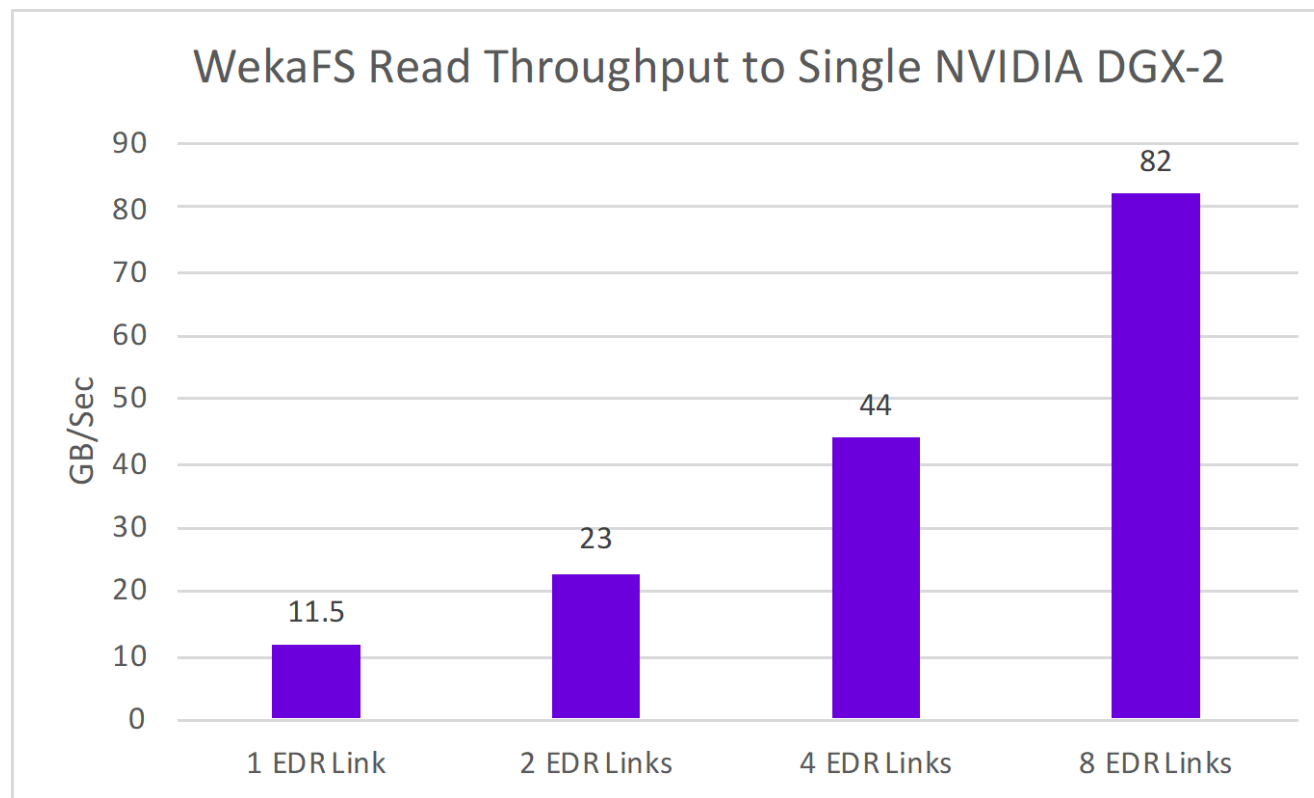
- Data compliance and security
 - in-line encryption support enables compliance
- Explain-ability and Reproducibility for experiments
 - instant space efficient snapshots make it easy to maintain versions
 - Snap2object retains versions for reproducibility and explain-ability
- Hybrid workflows
 - Dev and Test experiments in the public cloud, data mobility and rehydration on-premise for production

Pillars of AI Trust



WekaFS Delivered 82GB/sec to a single NVIDIA DGX-2

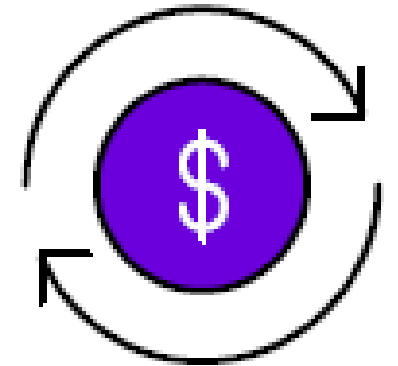
- WekaFS with GPUDirect Storage fully saturates an InfiniBand EDR link, delivering full bandwidth to data hungry applications
- Performance scaled linearly as more EDR links were added
- WekaFS achieved 82GB/sec to a single NVIDIA DGX-2 across 8 EDR links using 2 Supermicro BigTwin servers



NVIDIA and Weka are currently running joint GPUDirect Storage beta program with customers and partners!

LOSF – Lots of Small Files

- Eliminating silos and multiple copies, but providing single storage platform for entire data pipeline
- Best scalability up-to EB's of storage with trillion of files across directories and single directory
- Best agility with data management across the edge, core and cloud
- Best TCO, with performance at scale
 - leverage NVMe flash for performance and object store for capacity
 - built in data protection eliminates need for another solution



Marquee customers



“We looked at our legacy architecture and instead of taking an evolutionary step and upgrading every component, we took the revolutionary approach. Weka cost-effectively enables both the use of POSIX and object storage with performance and latency that is far superior to any other solution.”

Bridget Collins, Chief Information Officer

Electric Car Company

*WekaIO demonstrated that it was the only file system that could **fully saturate the GPU cluster**. With WekaIO, the data scientists were able to significantly improve productivity by removing time consuming data copy tasks into local disks. In addition WekaIO provided **seamless integration to our massive training system data lake**.*

Thaddeus Fortenberry, Autopilot Infrastructure Architect



*WekaIO was the clear choice for our DNN training...**standard NAS would not scale** and Matrix [was] the **most performant of all the parallel file systems** we evaluated...we really liked that it was hardware-independent allowing us better **control over our infrastructure costs**.*

Dr. Xiaodi Hou, Co-founder and CTO



We built a GPU farm, and we needed a high-speed data pipe to feed it. We evaluated open source solutions, HDFS, and the public cloud. We chose Weka for its ability to provide cost-effective, high-bandwidth I/O to our GPUs, product maturity, customer references, and stellar on-demand support

Paul Liu, Engineering Operations Lead



Weka's storage scalability and the ability to grow the infrastructure without losing performance, was a key factor in the decision to select the Weka file system.

Oren Ben Ibghei, Infrastructure IT



WEKA

Panel Questions and Audience Surveys



▶ Panel Question # 1

- Clearly, the training problem is as much a storage networking and access issue as it is a volume issue. What sort of architectures are best for performing autonomous vehicle training?
 - NVIDIA
 - Weka
 - b-plus

Audience Survey Question #1

- Is your organization more concerned about storage for data acquisition, training, or operation of AVs? (check one):
 - Our primary concern is on-vehicle storage for data acquisition: 13%
 - Our primary concern is on-vehicle storage for data during AV operation: 7%
 - Our primary concern is on-vehicle storage for both data acquisition and AV operation: 30%
 - Our primary concern is storage in the lab/datacenter for AI/ML training: 23%
 - We are not concerned/no opinion: 23%
 - Other: 3%

▶ Panel Question #2

- Test vehicles have many of the same data storage challenges that training configurations do. What storage architectures and technologies work well for these applications?
 - b-plus
 - Weka
 - NVIDIA

Audience Survey Question #2

- When you consider solutions for AI training and data acquisition, what factor is most important to your organization? (check one):
 - Cost: 23%
 - Storage capacity: 13%
 - Storage performance: 45%
 - Storage networking: 10%
 - Future expandability: 3%
 - Other issues: 6%

▶ Panel Question # 3

- When optimizing storage performance for AI training and validation, what factors should be considered?
 - Weka
 - NVIDIA
 - b-plus

Audience Q&A



Thank You For Attending



G2M
RESEARCH